Beyond the
 Virtual Intracranial Stenting Challenge 2007:
 non-Newtonian and flow pulsatility effects
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8 Abstract

The Virtual Intracranial Stenting Challenge 2007 (VISC'07) is becoming a g standard test case in computational minimally-invasive cerebrovascular in-10 tervention. Following views expressed in the literature and consistent with 11 the recommendations of a report, the effects of non-Newtonian viscosity and 12 pulsatile flow are reported. Three models of stented cerebral aneurysms, 13 originating from VISC'07 are meshed and the flow characteristics simulated 14 using commercial Computational Fluid Dynamics (CFD) software. We con-15 clude that non-Newtonian and pulsatile effects are important to include in 16 order to discriminate more effectively between stent designs. 17

¹⁸ Key words: cerebral aneurysm, visc'07, stent

¹⁹ 1. Introduction

The work presented here uses benchmark models from the Virtual In-20 tracranial Stenting Challenge (VISC 2007), an international initiative to as-21 sess the effectiveness of state-of-the-art numerical modelling of blood flow in 22 stented cerebral aneurysms. The results submitted to VISC'07 by six simu-23 lation teams (Radaelli et al. 2008) highlight the desirability of considering 24 the effects of non-Newtonian viscosity and flow pulsatility in future work for 25 purposes of clinical relevance, both of which were included in our studies 26 briefly reported here. 27

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28 2. Methods

The Fluent code was used for the simulations. The following boundary conditions were set: uniform velocity with 2.36 $\frac{g}{s}$ mass flow rate at the inlet, zero gauge pressure on the outlet and no slip walls, as set by VISC'07.

A steady-state laminar solver was used with second order upwind momen-32 tum discretization and SIMPLE pressure-velocity coupling. The fluid flowing 33 in the artery was initially defined as water (as requested by VISC'07), and 34 later it was changed to blood with density (ρ) 1060 $\frac{kg}{m^3}$ and viscosity (μ) 4 cP. Since a Newtonian model is prone to underestimate the WSS in a CFD 35 36 analysis at lower velocity gradients (Chen et al. 2006, Lee and Steinman 37 2006, Gijsen et al. 1999a,b), it was decided to investigate a non-Newtonian 38 formulation as well. The Fluent power-law option for dynamic viscosity (Flu-39 ent 2006) was used, as no one model is universally accepted and this is a valid 40 option at lower shear rates (Johnson *et al.* 2004, Shibeshi and Collins 2005): 41

$$\mu_{\min} < \mu = k \cdot \dot{\gamma}^{n-1} < \mu_{\max} \tag{1}$$

where μ is the dynamic viscosity in $\frac{\text{kg}}{\text{ms}}$, k is the consistency index whose value is $0.0161 \frac{\text{kg s}^{n-2}}{\text{m}}$, n the power-law index is 0.63, and $\dot{\gamma}$ is the shear rate in s⁻¹ (Owen *et al.* 2005). μ_{min} and μ_{max} are lower and upper limits of the power-law function and were set to $10^{-5} \frac{\text{kg}}{\text{ms}}$ and $1 \frac{\text{kg}}{\text{ms}}$ respectively.

In order to address the inclusion of pulsatility (c.f. Radaelli et al. 2008 46 and others), unsteady simulations were configured for the unstented and the 47 three stented cases. The inlet waveform for a basilar artery (Ford *et al.* 2008) 48 was slightly modified as follows: the mean flow rate was set to the steady-49 state value of $2.36 \frac{g}{s}$ as specified by VISC'07 and implemented in Fluent as 50 a uniform velocity profile of $0.179 \frac{\text{m}}{\text{s}}$; the pulse rate was set to 70 beats 51 per minute; and the waveform was slightly smoothed in order to reduce the 52 number of time steps needed to represent the whole cycle. 53

A standard grid independency procedure on the stented aneurysm models was carried out, and a suitable meshing of 2.30 million elements meshes was selected.

57 3. Results

For brevity, we focus the results on two regions of interest. (i) The aneurysm Neck Section, which corresponds to the minimum section area of the aneurysm and is comparable with that of cut-plane P2 in Radaelli ⁶¹ et al. 2008. (ii) Segment x, the first $\frac{1}{3}$ aneurysm volume immediately after ⁶² the Neck Section. Results are given in terms of mass flow rate and average ⁶³ Wall Shear Stress (WSS).

64 3.1. Newtonian vs. non-Newtonian

Referring to the table of results for steady-state (Table 1), the non-Newtonian case significantly increases dynamic viscosity and slightly modifies mass flow rate in the lower aneurysm area resulting in a much higher average WSS. The Newtonian models overestimate mass flow rate by about 3% for Stent 1 and Stent 2 and underestimate by just under 2% for Stent 3, whereas the average WSS in the Newtonian models is consistently underestimated by 15-20%.

Table 1: Comparison between unstended and stented cases for steady-state flow. Percentages refer to difference between stented case and unstended artery.

	Mass Flow (g/s)	Average Dynamic Viscosity	Average WSS (Pa)
Case	through Neck Section	(cP = mPa s)in Segment x	in Segment x
Unstented artery	0.2800	7 149	2.057
non-Newtonian	0.3809	1.142	2.037
Stent 1	0.3391	4.000	1.091
Newtonian	-11.0 %	-44.0 %	-46.9 %
Stent 2	0.3427	4.000	1.054
Newtonian	-10.0 %	-44.0 %	-48.8 %
Stent 3	0.2738	4.000	0.960
Newtonian	-28.1 %	-44.0 %	-53.3%
Stent 1	0.3268	8.003	1.296
non-Newtonian	-14.2 %	+12.1~%	-37.0 %
Stent 2	0.3320	7.938	1.282
non-Newtonian	-12.8 %	+11.1 %	-37.6 %
Stent 3	0.2785	8.555	1.195
non-Newtonian	-26.9 %	+19.8~%	-41.9 %

The results do not contradict Gijsen *et al.* (1999a,b), who, using both experiments and simulations, essentially state the importance of non-Newtonian (shear-thinning) blood modelling since it alters significantly the velocity profiles. As a non-Newtonian model produces higher fluid viscosities in the aneurysm region (where the shear rate is low) compared to the Newtonian ⁷⁷ model, this implies that the fluid tends to reduce its speed much more quickly
⁷⁸ inside the aneurysm, and hence the non-Newtonian model produces a smaller
⁷⁹ mass flow rate. Also, the lower velocity gradient promotes a lower WSS while
⁸⁰ a higher viscosity promotes a higher WSS.

In the lower aneurysm, the effect of the increased viscosity is dominant and the Newtonian model significantly underestimates the average WSS. Overall, it seems that the non-Newtonian hypothesis redistributes the velocity profiles and the WSS in a more uniform and smooth way and thus peaks are smoothed out (Figure 1).



Figure 1: WSS and velocity profiles in aneurysm region for stent 3 steady simulation: Newtonian versus non-Newtonian: (a) WSS, Newtonian case; (b) WSS, non-Newtonian case; (c) velocity profiles, Newtonian case; (d) velocity profiles, non-Newtonian case

86 3.2. Pulsatile flow

In Figure 2 the mass flow rate entering the aneurysm (i.e. crossing the Neck Section) is shown. The pulse cycle in the main artery is also shown scaled to $\frac{1}{5}$ -th of its amplitude.

The mass flow rate entering the aneurysm in the unstented case at time 0 s is equal to $0.3488 \frac{g}{s}$ (15% of the mass flow rate in the main artery). This ratio remains in the range from 10% to 20% for all the cases investigated and for most of the pulse cycle, except when the mass flow rate in the artery drops to its minimum.

The presence of the stent reduces the mass flow rate in the aneurysm region and also promotes small changes in the phase between the mass flow rate in the main artery and in the aneurysm. In fact, the main pulse cycle is



Figure 2: Mass flow through Section 9

⁹⁸ reflected in the aneurysm mass flow rate with a minimum phase delay from ⁹⁹ 0 to 0.5 s. However, the maximum peak in the aneurysm mass flow rate, ¹⁰⁰ which is found at ≈ 0.57 s for each of the four simulations, anticipates the ¹⁰¹ corresponding peak in the main artery, which is found at 0.59 s. The change ¹⁰² in the phase shift, even if small, together with the change in mass flow ratio ¹⁰³ along the cycle suggest the relevance of adopting unsteady simulations for ¹⁰⁴ better accuracy.

The third stent is particularly efficient in reducing the mass flow rate entering the aneurysm, in particular in the first half of the pulse cycle with reductions ranging from 20 % to 50 % when compared to the unstented artery. The third stent also shows better performance, when compared with the other two stents, for more than 75 % of the pulse cycle.

110 3.3. Evaluating three stents from VISC'07

¹¹¹ Considering the non-Newtonian blood model (see Table 1), the mass flow ¹¹² rates of stent 1 and stent 2 are not so different from each other. Stent 2 has ¹¹³ a higher mass flow rate through the Neck Section $(0.3320 \frac{\text{g}}{\text{s}} \text{ equal to a } 12.8 \%$ ¹¹⁴ reduction in the mass flow rate compared to the unstended case). Stent 3



Figure 3: WSS on surface of aneurysm for steady non-Newtonian simulations

appears to be much more effective in reducing the mass flow rate in the aneurysm since the blood crossing the Neck Section in this case amounts to $0.2785 \frac{g}{s}$ (a 26.9% reduction).

From these initial considerations stent 3 is expected to be a better clinical performer than the other two.

¹²⁰ Comparing the WSS in the unstended case with the three stended models ¹²¹ (Figure 3 and Table 1), the use of a stent appears to be very effective in ¹²² reducing the WSS.

123 4. Conclusions

The inclusion of non-Newtonian and pulsatile effects in the VISC'07 models are shown to be important. Stent 3 emerges as the best design, which is consistent with the results published in the literature.

127 Conflict of interest statement

The authors have no financial or personal relationships with other people or organisations that could inappropriately influence (bias) their work.

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