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NON-UNIFORM CORNER CUTTING

by

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The convergence of a non-uniform Abstract corner cutting process is differentiable investigated. It is shown that the limit curve will be provided the proportions of the within corner cuts are kept appropriate constraints.

Keywords Subdivision, corner cutting

1. Introduction

In paper [de Boor '871 it shown that "cutting corners" а recent was of "always works", control polygon in the sense that the limit curve will be а Lipschitz continuous. In wish this paper to show that the limit we curve will be differentiable under appropriate conditions the some on corner cutting process. The key analysis the choice of to the is а parameterization which itself satisfies the corner cutting process (rather than using а uniform diadic point parameterization in [Micchelli and as for Prautzsch '87] [Dyn, Gregory, Levin '88] uniform subdivision or schemes).

2. The corner cutting process

Let ${}^{0}_{fi} \in \mathbb{R}^{N}$, i = 0,...,n+1, denote a given sequence of initial of initial control points in \mathbb{RN} , ≥ 1 , which are defined at the parameter values ${}^{0}_{t0} < {}^{0}_{t1} < ... < {}^{0}_{tn+1}$. The corner cutting process is then defined by : For k = 0,1,2,...; for $i - 0,...,2^{k}n;$

(2.1)
$$\begin{cases} f_{2i}^{n+1} = (1-\alpha_{i}^{K})f_{i}^{K} + \alpha_{i}^{K}f_{i+1}^{K} \text{ at } t_{2i}^{K+1} = (1-\alpha_{i}^{K})t_{i}^{K} + \alpha_{i}^{K} + \alpha_{i+1}^{K}t_{i+1}^{K} ,\\ f_{2i+1}^{k+1} = \beta_{i}^{k}f_{i}^{k} + (1-\beta_{i}^{k})f_{i+1}^{k} \text{ at } t_{2i+1}^{k+1} = \beta_{i}^{k}t_{i}^{k} + (1-\beta_{i}^{k})t_{i+1}^{k} ,\end{cases}$$

where

(2.2)
$$\begin{array}{ccc} \alpha_{i}^{k} > 0 & , & \beta_{i}^{k} > 0 & \text{and} & j - \alpha_{i}^{k} - \beta_{i}^{k} > 0 & . \\ \text{Denote by } f^{k} & \text{the control polygonwith vertices } f_{i}^{k}, & i = 0, \dots, 2^{k}n+1 \end{array}$$

Then (2.1) is a process whereby f^{k+1} is created by corner cutting of the polygon f^k . In general, this process is non-uniform since the proportions $\begin{pmatrix} k \\ \alpha i \end{pmatrix}$, $\begin{pmatrix} k \\ \beta i \end{pmatrix}$ of the corner cuts can depend both on i and k.

For the purposes of the analysis, the control points $\begin{Bmatrix} k \\ f_1 \end{Bmatrix}$ aer associated with parameter points $\begin{Bmatrix} k \\ t_1 \end{Bmatrix}$ which also satisfy the corner cutting process, see (2.1). These parametric points always form a strictly monotonic increasing set $\begin{smallmatrix} k \\ t_0 < t_1 \\ k < ... < \begin{smallmatrix} k \\ t_2 \\ k_{n+1} \\ k \end{bmatrix}$ since

(2.3)
$$\begin{array}{cccc} k & k+1 \\ t_i & t_{2i} & k+1 \\ t_{2i+1} & t_{2i+1} & k \\ t_{i+1} & i = 0, \dots, 2^k n \end{array} ,$$

for α_i^k , β_i^k satisfying (2.2). The control polygon f^k can thus be identified unambiguously as the piecewise linear interpolant

$$(2.4) \quad f^{k}(t) := \left\{ \frac{k}{ti+1} - t \atop k \atop ti+1 - ti} \right\} f^{k}_{i} + \left[\frac{t - k}{k} \atop ti+1 - ti} \right] f^{k}_{i+1} , t \in \left\{ \frac{k}{ti}, \frac{k}{ti+1} \right\} , i = 0, \dots, 2^{k} n.$$

We propose to analyse the convergence properties of the component functions of f^k and hence it suffices from now on to consider the scalar case N=1, see Figure 1.





It follows from (2.3) that ${k \choose t_0}^{\infty} k=0$ and ${k \choose t_2 k_{k=0}}^{\infty} k=0$ from monotonic increasign and decerasing sequences bounded above and below by t_1^0 and t_n^0 rerspectively.

Hence there exist

(2.5)
$$a := \lim_{k} t_0^k \le t_1^0 \text{ and } b := \lim_{k} t_{2k_n}^k \ge t_n^0.$$

We than make use of the uniform norm

(2.7)
$$\|f\| = \max_{a \le t \le b} |f(t)| , f \in C[a,b] ,$$
on the interval [a,b].

3. Cutting corners is C^0

Although our main purpose is to find conditions under which the corner cutting process has a C^1 limit, we begin by considering a C^0 analysis. We will show that $\{f^k\}^{\infty}k=0$ defines a Cauchy sequence no C[a,b] and for this we require the following Lemma:

Lemma 3.1

$$(3.1) |f^{k+p} - f^k| \le 2 \max_i |\Delta_{f_i}^k| \forall k, p \ge 0 ,$$

where

$$(3.2) \qquad \qquad \Delta \begin{array}{c} k \\ f_i \end{array} := \begin{array}{c} k+p \\ f_{i+1} \end{array} - \begin{array}{c} k \\ f_i \end{array}$$

Proof Consider $f^{k+p}(t)$ and $f^{k}(t)$ on $\begin{bmatrix} t^{k+p}, t^{k+p} \\ 2^{p}i & 2^{p}(i+1) \end{bmatrix}$. From (2.3) we have (3.3) $\begin{array}{c} k \\ t_{i} < k \\ 2^{p}i \\ 2^{p}i \\ 2^{p}(i+1) \\ k \\ t_{i+2} \end{array}$

and since the process (2.1) defines a convex combination we can obtain

(3.4)
$$m_{i} \leq f_{j}^{k+p} \leq M_{i}, \quad \forall j = 2^{P}i, ..., 2^{P}(i+1),$$

where

(3.5)
$$m_i = \min \left\{ \begin{array}{c} k & k & k \\ f_i & f_{i+1} & f_{i+2} \end{array} \right\} , \quad M_i = \max \left\{ \begin{array}{c} k & k & k \\ f_i & f_{i+1} & f_{i+2} \end{array} \right\} .$$

Hence

$$m_{i} \leq f^{k+p}(t) \leq M_{i} - m_{i} \leq f^{k}(t) \leq M_{i}$$

which gives
(3.6)
$$|f^{k+p}(t) - f^{k}(t)| \le M_{i} - m_{i} \le |f_{i+1} - f_{i}| + |f_{i+2} - f_{i+1}|$$

 $\forall t \in \begin{bmatrix} t^{k+p}, t^{k+p} \\ 2^{P}i & 2^{P}(i+1) \end{bmatrix}$ and the Lemma follows.

Lemma 3.1 suggests an analysis of the difference process which is obtained from (2.1) as

(3.7)
$$\begin{cases} \Delta_{f} {}_{2i}^{k+1} = (1 - \alpha_{i}^{k} - \beta_{i}^{k}) \Delta_{f} {}_{i}^{k}, \\ \Delta_{f} {}_{2i+1}^{k+1} = \beta_{i}^{k} \Delta_{f} {}_{i}^{k} + \alpha_{i+1}^{k} \Delta_{f} {}_{i+1}^{k}. \end{cases}$$

Let

(3.8)
$$\begin{cases} \overline{\alpha} = \lim_{k} \max_{i} \alpha_{i}^{k}, \ \underline{\alpha} = \underline{\lim} \min_{i} \alpha_{i}^{k}, \\ \overline{\beta} = \lim_{k} \max_{i} \beta_{i}^{k}, \ \underline{\beta} = \lim_{i} \max_{i} \beta_{i}^{k}. \end{cases}$$

Then we have the following:

Theorem 3.2 (C° convergence) The corner cutting process defined by (2.1) and (2.2) converges to a C° limit if

(3.9)
$$\underline{\alpha} > 0$$
, $\underline{\beta} > 0$ and $1 - \overline{\alpha} - \overline{\beta} > 0$

Proof It follows from the definition of the difference process (3.7) that

(3.10)
$$\max_{i} |\Delta_{f_{i}}^{k+1}| \leq B_{k} \max_{i} |\Delta_{f_{i}}^{k}| ,$$

where

$$(3.11) B_k = \max_i \left\{ 1 - \frac{k}{\alpha_i} - \frac{k}{\beta_i}, \frac{k}{\beta_i} + \frac{k}{\alpha_{i+1}} \right\} .$$

Moreover, it can be shown that

$$(3.12) B_k \le B < 1$$

for some constant B, independent of k, if (3.9) holds. Hence the differences are contracting and from Lemma 3.1 it follows that $\{f^k\}_{k=0}^{\infty}$ defines a Cauchy sequence on C[a,b] which completes the proof.

Conditions (3.9) require $(\underline{\alpha}, \underline{\beta})$ and $(\overline{\alpha}, \overline{\beta})$ to lie strictly within the region Ω_0 depicted in Figure 3.1. In particular $(0,0) < (\underline{\alpha}, \underline{\beta}) \le (\overline{\alpha}, \overline{\beta}) < (\frac{1}{2}, \frac{1}{2})$



Figure 3.1

C° limitdifferent sufficient condition for а In [de Boor '87] is а а is for argument used to prove convergence a more general corner cutting conditions process. However, our is to find under which the purpose a C^1 limit (2.1)process has and hence we have found it appropriate to C^0 C^1 analysis here. The separate analysis develop а makes of use the following observation:

Remark 3.3 The parameteric points ${k \atop ti}^{2k}_{i=0}^{2k}$ become dense in [a,b].

Proof Since the parameteric points satisfy the corner cutting process, it follows that

$$\left[\Delta_{t2i+1}^{k+1} = \beta_i^k \Delta_{ti}^k + \alpha_{i+1}^k \Delta_{ti}^k\right],$$

of. (3.7), and that

(3.14)
$$\max_{i} |\Delta_{ti}^{k+1}| \leq B_k \max_{i} |\Delta_{ti}^{k}|$$

of. (3.10). Since (3.12) holds (under the conditions (3.9)) we have $\lim_{k} \max_{i} |\Delta_{t_{i}}^{k}| = 0.$ 4. Cutting corners is C¹

To analyse C^1 convergence, consider the divided difference process defined from (3.7) and (3.13) by

(4.1)
$$\begin{cases} d_{2i}^{k+1} = d_i^k & \text{at} \quad t_{2i}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} = (1-\theta_i^k)d_i^k + \theta_i^k d_{i+1}^k & \text{at} \quad t_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} & d_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} & d_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} & d_{2i+1}^{k+1} \\ d_{2i+1}^{k+1} & d_{2i+1}^{k+1} \\$$

where

We then have:

Theorem 4.1 If the divided difference scheme converges uniformly to d ϵ C[a,b] (with respect to the parametric points $\begin{cases} k \\ ti \end{cases}$), then the corner cutting scheme converges uniformly to $f \epsilon$ C¹ [a,b], where f' = d. Proof Let H_k denote the piecewise cubic Hermite interpolant such that

(4.4)
$$H_k \begin{pmatrix} k \\ ti \end{pmatrix} = \begin{pmatrix} k \\ fi \end{pmatrix}$$
 and $H'_k \begin{pmatrix} k \\ ti \end{pmatrix} = \begin{pmatrix} k \\ di \end{pmatrix}$, $i = 0, \dots, 2^k n$

Then for $t \in \binom{k}{ti}, \frac{k}{ti+1}$ with $\theta = (t - \frac{k}{ti})/\Delta \frac{k}{ti} + \theta^2 (-2\theta + 3) \frac{k}{ti+1}$ (4.5) $H_k(t) = (1-\theta)^2 (2\theta+1) \frac{k}{ti} + \theta^2 (-2\theta+3) \frac{k}{ti+1} + (1-\theta)^2 \theta \Delta \frac{k}{ti} \frac{k}{di} + \theta^2 (\theta-1) \Delta \frac{k}{ti} \frac{k}{di+1}$

and

(4.6)
$$H'_{k}(t) = (-3\theta^{2} + 2\theta + 1)\frac{k}{di} + (3\theta^{2} - 2\theta\theta\frac{k}{di+1})$$

Also, let d be the divided difference control polygon (piecewise linear interpolant) defined for $t \in \begin{bmatrix} k & k \\ t_i & t_{i+1} \end{bmatrix}$ by

(4.7)
$$d_k(t) = (1-\theta) \frac{k}{di} + \theta \frac{k}{di+1}$$

where $d^k \rightarrow d$ uniformly on C[a,b] by hypothesis. Then subtracting (4.6) from (4.7) leads to

(4.8)
$$||d^{k} - H'_{k}|| \leq \frac{3}{4} \max_{i} |\frac{k}{di+1} - \frac{k}{di}|$$

Thus

(4.9)
$$\lim_{k} ||d - H'_{k}|| \le \lim_{k} ||d - d^{k}|| + \lim_{k} ||d^{k} - H'_{k}|| = 0$$

i.e. $H'_k \rightarrow d$ uniformly. (The right hand side of (4.8) converges necessarily to zero if lim dk = d ε C[a,b] and the parametric points become dense in [a,b].) We now show that $\{H_k\}^{\infty}k=0$ converges on $C^1[a,b]$. Assume, without loss of qenerality, that ${}^0_{f0} = {}^0_{f1} = {}^0_{f2} = 0$. Then at the kth step ${}^k_{f0} = {}^k_{f1} = {}^k_{f2} = 0$ and ${}^k_{d0} = {}^k_{d1} = 0$. (This reflects the "local suppor" nature of the corner cutting process.) Thus, necessarily, f(a) = d(a) = 0 and $H_k(a) = 0$.

Define

(4.10)
$$f(t) := \int_a^t d(t) dt$$

Then

(4.11)
$$\|\mathbf{f} - \mathbf{H}_{k}\| = \max_{a \prec t \le b} |\int_{a}^{t} \left\{ d(\bar{t}) - \mathbf{H}_{k}(\bar{t}) \right\} d\bar{t} | \le (b-a) \|d - \mathbf{H}_{k}\|.$$

Hence, H_k converges uniformly to $f \in C^1$ [a,b], where f = d. Finally, since (4.12) $\|f - f^k\| \le \|f - H_k\| + \|H_k - f^k\| \le \|f - H_k\| + \frac{1}{2} \max_i (\Delta t_i^k)^2 \|H_k^{"}\|$

(using the Cauchy remainder for linear interpolation), it follows that the control polygon fk of the corner cutting process converges uniformly to $f \in C^1[a,b]$, (where we again note that the parametric points become dense in [a,b], see Remark 3.3).

Theorem 4.1 indicates that, in order to prove C^1 convergence of the corner cutting process, we should find conditions for which the divided difference process (4.1) has a C^0 limit. Now the process (4.1) has the property that the image set

(4.13)
$$I_k = ((t, d^k(t)) \in R^2 : t \in [a, b])$$

lies on the initial image set $I_0 \ \forall k$. It is thus tempting to conclude that $d^k = d^0 \in C[a,b] \ \forall k$. However, this is an incorrect argument since $d^k(t)$ has been defined as the piecewise linear interpolant with respect to the partition $\frac{k}{t0} < \frac{k}{t1} < ... < \frac{k}{tn}$ of the original corner cutting process. Thus the analysis of C^o convergence of the divided difference process must be constructed with more care and, following the approach of section 3, we have: Lemma 4.2

$$(4.14) \|d^{k+p} - d^k\| \le 2 \max_i |\Delta_{di}^k| \quad \forall \ k,p \ge 0 .$$

Theorem 4.3 (C^1 convergence) The divided difference process (4.1) converges uniformly to a C^0 limit (and hence the corner cutting process converges uniformly to a C^1 limit) if

(4.15)
$$\overline{\alpha} > 0$$
, $\underline{\beta} > 0$, $2\overline{\alpha} + \overline{\beta} < 1$ and $\overline{\alpha} + 2\overline{\beta} < 1$.

The proof of Lemma 4.2 is identical to that of Lemma 3.1. The proof of Theorem 4.3 requires the following additional lemma: Lemma 4.4 Let

(4.16)
$$\frac{k}{r_i} := \Delta \frac{k}{t_{i+1}} / \Delta \frac{k}{t_i}$$

and assume that (4.15) holds. Then there exist r and R such that

$$(4.17) 0 < r \le \frac{k}{ri} \le R < \infty \forall i, k.$$

Proof From (3.13) we obtain the following non-linear relations: $\begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}$

Hence, if $r \leq \frac{k}{r_i} \leq R$ \forall i,k, we have

$$\begin{bmatrix} k & k \\ \beta_i & + & \alpha_{i+1}r \end{bmatrix} / \begin{bmatrix} 1 - \frac{k}{\alpha_i} & - & \beta_i \end{bmatrix} \leq \frac{k+1}{r2i} \leq \begin{bmatrix} k & k & k \\ \beta_i & + & \alpha_{i+1}R \end{bmatrix} \begin{bmatrix} 1 - \frac{k}{\alpha_i} & - & \beta_i \end{bmatrix} ,,$$

$$\begin{bmatrix} 1 & -\frac{k}{\alpha_{i+1}} & - & \beta_{i+1} \end{bmatrix} / \begin{bmatrix} k & k & k \\ \beta_i & r & \alpha_{i+1} \end{bmatrix} \leq \frac{k+1}{r2i+1} \leq \begin{bmatrix} 1 - \frac{k}{\alpha_{i+1}} & - & \beta_{i+1} \end{bmatrix} / \begin{bmatrix} k & k & k \\ \beta_i & r & \alpha_{i+1} \end{bmatrix} .$$

Thus, we require r and R such that

$$\begin{bmatrix} k & k \\ \beta_i & + & \alpha_{i+1} \end{bmatrix} / \begin{bmatrix} 1 - \alpha_i^k & - & \beta_i^k \end{bmatrix} \le R , \quad \begin{bmatrix} 1 - \alpha_{i+1}^i & - & \beta_{i+1} \end{bmatrix} / \begin{bmatrix} k & k & k \\ \beta_i^k & /R & + & \alpha_{i+1} \end{bmatrix} \le R ,$$
 and

$$r \leq \begin{bmatrix} k & k \\ \beta_i & + & \alpha_{i+1}r \end{bmatrix} / \begin{bmatrix} 1 - \frac{k}{\alpha_i} & - & k \\ - & \beta_i \end{bmatrix}, r \leq \begin{bmatrix} 1 - \frac{k}{\alpha_{i+1}} & - & k \\ - & \alpha_{i+1} \end{bmatrix} / \begin{bmatrix} k & k & k \\ \beta_i & r & + & \alpha_{i+1} \end{bmatrix}$$

Therefore

$$(4.19) \quad \max_{i} \left\{ \beta_{i}^{k} / \left[1 - \frac{k}{\alpha_{i}} - \frac{k}{\beta_{i}} - \frac{k}{\alpha_{i}+1} \right] , \quad \left[1 - \frac{k}{\alpha_{i}+1} - \frac{k}{\beta_{i}} \right] / \frac{k}{\alpha_{i}+1} - \frac{k}{\alpha_{i}+1} \right\} \leq R ,$$

and

$$(4.20) \quad r \leq \max_{i} \left\{ \beta_{i}^{k} / \left[1 - \frac{k}{\alpha_{i}} - \frac{k}{\beta_{i}} - \frac{k}{\alpha_{i}+1} \right] \quad , \quad \left[1 - \frac{k}{\alpha_{i}+1} - \frac{k}{\beta_{i}+1} - \frac{k}{\beta_{i}} \right] / \frac{k}{\alpha_{i}+1} \right\}$$

provided

(4.21)
$$1 - \frac{k}{\alpha i} - \frac{k}{\beta i} - \frac{k}{\alpha i + 1} > 0 \text{ and } 1 - \frac{k}{\alpha i + 1} - \frac{k}{\beta i + 1} - \frac{k}{\beta i} > 0.$$

Condition (4.17) is then beained under the hypothesis (4.15). Proof of Theorem 4.3 From (4.1) and (4.3) we obtain (4.22) $\begin{cases} \Delta_{d2i}^{k+1} = \theta_i^k \Delta_{di}^k , \\ \Delta_{d2i+1}^{k+1} = (1-\theta_i^k) \Delta_{di}^k , \end{cases}$ where $0 < \theta_i^k < 1$. Thus

$$(4.23) \qquad \qquad \max_i |\Delta_{di}^{k+1}| \leq C_k \quad \max_i |\Delta_{di}^k| \quad ,$$

where

and hence

$$(4.25) 0 < C_k < 1.$$

Condition (4.25) is not strong enough for our purposes and we wish to show that

for some constant C, independent of k. Now, from (4.3),

(4.27)
$$\theta_{i}^{k} = \frac{1}{1+1/r_{i}^{k}}, \quad 1-\theta_{i}^{k} = \frac{1}{1+r_{i}^{k}},$$

where

(4.28)
$$\hat{\mathbf{r}}_{i}^{k} = \frac{\mathbf{k}}{\alpha_{i+1}} \frac{\mathbf{k}}{\mathbf{r}_{i}} / \beta_{i}^{k}$$

Furthermore, by Lemma 4.4 (and the hypothesis (4.15)), there exist r and R such that

$$(4.29) 0 < \hat{\mathbf{r}} \leq \hat{\mathbf{r}}_{1} \hat{\mathbf{k}} \leq \hat{\mathbf{R}} < \infty$$

Thus

and (4.26) holds. Finally, it now follows from Lemma 4.2 that $\{d^k\}^{\infty} k=0$ defines a Cauchy sequence on C[a,b] and hence has limit $d \in C[a,b]$ say.

Conditions (4.15) for C¹ convergence require $(\underline{\alpha}, \beta)$ and $(\overline{\alpha}, \overline{\beta})$ to lie strictly within the region Ω_1 depicted in Figure 4.1 (cf. Figure 3.1).



Figure 4.1

In particular, $(0,0) < (\underline{\alpha},\underline{\beta}) < (\alpha,\beta) < (\frac{1}{3},\frac{1}{3})$ is a sufficient condition for a C¹ limit (i.e. corner cutting of proportions strictly less than one third ensures a C¹ limit). If $(\overline{\alpha},\overline{\beta})$ lies strictly outside the region Ω_1 , then convergence to a C¹ limit is no longer guaranteed. For example, with

 \wedge

$$\begin{array}{l} \overset{k}{\alpha_{i}} = \alpha \ \text{and} \ \beta_{i}^{k} = \beta \quad \forall \quad i, k, \ \text{it can be shown that} \ (\text{see } (4.22)) \\ \Delta_{d0}^{k+1} = \overset{k}{\theta_{0}} \Delta_{d0}^{k} = \overset{k}{\theta_{0}} \overset{k-1}{\theta_{0}} \ldots \overset{0}{\theta_{0}} \Delta_{d0}^{0} \end{array}$$

will not converge to zero if $2\alpha + \beta > 1$. This violates a necessary C^1 convergence condition. Similarly, by symmetry, $\alpha + 2\beta > 1$ is not allowable.

We have shown that the corner cutting process has a C^1 limit, under the conditions (4.15), with respect to a parameterization which is itself defined by the corner cutting method. We conclude by showing that this parameterization is regular in the case R^N , N > 1.

Theorem 4.5 (Regular parameterization) In the case of corner cutting in R^N , N > 1, the C^1 limit curve f of Theorem 4.3 is regular, i.e. $f(t) = d(t) \neq 0 \forall t$ [a,b], except for the singular cases, where, for some i,

(i)
$$\begin{array}{c} 0 \\ f_{i} \\ = \\ 0 \\ f_{i+1} \\ \end{array}$$
, or
(ii) $\begin{array}{c} 0 \\ f_{i+1} \\ = \\ (1-\theta) \\ f_{i} \\ \end{array}$, $\begin{array}{c} 0 \\ + \\ \theta \\ f_{i-1} \\ \end{array}$ for some $\theta > 0$.

Proof Let

(4.31)
$$J_k = \{ d^k(t) \in \mathbb{R}^N : t \in [a,b] \}$$

be the image set of $d^{k}(t)$. Then, following an earlier argument, we have $J_{k} \stackrel{c}{} J_{0} \forall k$, for a process of the form (4.1). Thus d(t) = 0 for some $t \in [a,b]$ implies that $d^{0}(t) = 0$ for some $t \in [a,b]$ and this can only

occur if $(i)_{di}^{0} = 0$ for some i or (ii) for $_{di}^{0} = -\theta_{di-1}^{0}$ some i and $\theta > 0$.

As a final comment, it should be noted that, because of the local nature of the corner cutting process (2.1), the convergence arguments presented here also apply to the case of closed polygons in \mathbb{R}^N , N > 1. This case can be treated as periodic date, where $\int_{fn}^{0} = \int_{fn+1}^{0} = \int_{f1}^{0}$ and in the process $\begin{pmatrix} k \\ \alpha_{2k} \\ n \end{pmatrix} = \begin{pmatrix} k \\ \alpha_{0} \\ k \end{pmatrix}, \quad \begin{pmatrix} k \\ \beta_{2k} \\ n \end{pmatrix} = \begin{pmatrix} k \\ \beta_{0} \\ k \end{pmatrix}.$

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