

## Application of SPH to solid mechanics problems

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## **Overview**

- Introduction/Motivation
- In-house SPH code overview
- Fluid-structure interaction
- Solid mechanics examples
- Solid mechanics current work



## Introduction/Motivation

## Introduction/Motivation

- Failure of materials and structures due to transient loading (e.g. impact, crash)
- Simulation tools are not always able to accurately predict behaviour
- SPH has attractive features:
  - Large deformations
  - Lagrangian
  - Treatment of fracture



## In-house SPH code overview

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Eulerian and Total Lagrangian kernel formulations

Constitutive models (elastic, elasto-plastic, composites)

Equations of state (Tait, Mie-gruneisen)

Boundary conditions (prescribed displacement, velocity, acceleration)

Body force

Multiple materials

Contact

Subcycling

Coupled to LLNL-Dyna3D FEM solver

Hypervelocity Impact (1997)





Experiment Image from Libersky et al (1993) J Comp Phys 109, 67-75



# Fluid-structure interaction

## **Fluid-structure interaction**

Interested in structural response

Sloshing ESA

Explosive forming

Ditching helicopter/aircraft

Extreme wave Buoy/wave impact

## **Analysis of Extreme Loading**

Applications:



## Sloshing

A cylindrical tank (with a hemi-spherical base):

- Partially filled
- Subjected to Constant frequency base excitation.



The measured parameters are:

- Sloshing force (the reaction force at the attachment of the tank support structure to the shaker table),
- Interface force between the tank and the support structure,
- Fluid motion

## **Sloshing**

#### Constant sweep frequency



## **Sloshing**



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## **Explosive forming**

Explosive Energy Transfer Medium Workpiece Explosive forming • Main components involved: • **Explosive Charge** ٠ **Energy Transfer Medium** • Forming Die + Clamping • Workpiece •

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## **Explosive forming**



## Low angle water impact

- Part of FP7 SMAES project, using guided water impact facility (INSEAN) developed to allow high-velocity, low angle water impact experiments.
  - > 47 tests on flat & curved thick plates
  - 17 tests on metallic and composite deformable plates
  - > 2 tests on stiffened panel component







## Low angle water impact

Structural component (underwater view)







## Low angle water impact





# Solid mechanics examples



Explosively driven

Mock-Holt Simulation - Standard SPH (Ra Time = 5.6153e-040





Mass (g)



--- Experiment

100

<mark>س</mark> 80 60

40 20

0

0



**Bird Strike** 



0.2 0.4 0.6 0.8 Normalized leading edge length

0.8

1



## × ×

Vignjevic et al. (2013) International Journal of Impact Engineering, 60, 44-57

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### Ice Impact





## **Ballistic/Hypervelocity Impact**



## Machining









The work presented forms part of H2020 project EXTREME (grant agreement No 636549) on dynamic loading of composite structures

### www.extreme-h2020.eu





Dynamic loading of composite materials

- Strain softening
- Interaction area damage
- FE-SPH coupling and adaptivity

Applications

- Birdstrike and debris impact on flat panel
- Birdstrike fan, engine cowl, leading edge
- Debris impact on stiffened panel
- Blade-off





 During FEM simulations of impact on CFRP excessive element deletion can be a problem







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## Non-local properties – strain softening

SPH as Non-local Regularisation Method







Vignjevic et. al. (2014) Comput. Methods Appl. Mech. Engrg. 277, 281–304

#### FEM

#### SPH

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## **Interaction Area Damage**



 $F = \sigma \cdot A$ 

Swegle Interaction Area\*

Force on particle *i* 

$$\langle m_i \ddot{u}_i \rangle = \langle F_i \rangle = -\sum_{j=1}^{np} m_i m_j \left( \frac{P_i}{\rho_i^2} + \frac{P_j}{\rho_j^2} \right) \nabla_i W_{ij}$$

can be rewritten as:

$$\begin{split} F_i &= -\sum_{j} \left[ P_i \frac{\rho_j}{\rho_i} + P_j \frac{\rho_i}{\rho_j} \right] A_{ij} \\ \text{with: } A_{ij} &= V_i V_j \nabla_i W_{ij} \end{split}$$

\* J.W. Swegle, Conservation of momentum and tensile instability in particle methods., USA: Sandia National Laboratories, 2000. SAND2000-1223

## **Interaction Area Damage**



Standard approach (Kachanov, Lemaitre) in damage mechanics:

- A damage variable, D represents an effective surface density  $\tilde{A}$  due to presence of microscopic cracks or voids within the material

$$\tilde{A} = A\left(1 - D\right)$$

• Leads to concept of an effective stress

$$\tilde{\sigma} = \frac{\sigma}{(1-D)}$$

\* Kachanov LM. Time of the rupture process under creep conditions. Izv. Akad. Nauk., S.S.R., Otd Tech Nauk 1958;8(8):26-31

## **Interaction Area Damage**

• Impact on brittle material modelled with isotropic elastic with failure stress;



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## **Interaction Area Damage**



## **Coupling Algorithms**

- Belytschko
- Huerta and Fernandez-Mendez

Domain discretised with a set of particles and a set of FE, where particles are not exactly located at the FE nodes ;

Blended shape function methods with higher order reproducibility;

Particle shape functions are modified to improve the quality of the approximation taking into account the interpolation functions and positions of active FE nodes and the particles;

FE shape functions for the non active elements are switched off;

Interpolation space within element replaced by contributions from neighbouring particles and red nodes only;

