

# 1 **Solid-State Additive Manufacturing of Porous Ti-6Al-4V by Supersonic** 2 **Impact**

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16  
17 Additive manufacturing of functional metallic parts based on layer-by-layer melting and  
18 solidification suffers from the detrimental effects of high-temperature processing such as large  
19 residual stresses, poor mechanical properties, unwanted phase transformations, and part distortion.  
20 Here we utilize the kinetic energy of powder particles to form solid-state bonding and overcome  
21 the challenges associated with the high temperature processing of metals. Specifically, we  
22 accelerated powders to supersonic impact velocities (~600 m/s) and exploited plastic deformation  
23 and softening due to high strain rate dynamic loading to 3D print Ti-6Al-4V powders at  
24 temperatures (800 °C, 900 °C) well below their melting point (1626 °C). By using processing  
25 conditions below the critical powder impact velocity and controlling the surface temperature, we  
26 created mechanically robust, porous metallic deposits with spatially controlled porosity (apparent  
27 modulus 51.7±3.2 GPa, apparent compressive yield strength 535±35, porosity 30±2%). When the  
28 mechanical properties of solid-state 3D printed Ti-6Al-4V were compared to other additive  
29 manufactured techniques, the Young's modulus was similar, but the compressive yield strength  
30 was up to 42% higher. Post heat treatment of solid-state printed porous Ti-6Al-4V modified the  
31 mechanical behavior of the deposit under compressive loading. Additionally, the 3D printed  
32 porous Ti-6Al-4V was shown to be biocompatible with MC3T3-E1 SC4 murine preosteoblast  
33 cells, indicating the potential biomedical applications of these materials. Our study demonstrates  
34 a single-step, solid-state additive manufacturing method for producing biocompatible porous metal  
35 parts with higher strength than conventional high temperature additive manufacturing techniques.

36 Keywords: Cold spray, Additive manufacturing, Cellular structure, Titanium alloy,  
37 Biocompatible

## 38 **1. Introduction**

39 Conventional processing routes to fabricate metallic cellular structures constrain material  
40 selection [1–3] and part geometry, which is mostly limited to planar shapes [4,5]. Additionally,  
41 powder metallurgy based methods for creating cellular solids restrict pore size and shape while  
42 requiring post processing steps to remove sacrificial space holders (i.e. by dissolution or thermal  
43 degradation) [2]. The need for specific mechanical and functional properties as well as  
44 manufacturing flexibility for a wide range of metallic materials has brought interest in using  
45 additive manufacturing techniques in various industrial applications [6–10]. Additive  
46 manufacturing is promising for fabricating complex geometries but has several drawbacks  
47 associated with the high temperature processing of metals that often result in undesired mechanical  
48 properties [8,11–14].

49 Supersonic powder deposition (cold spraying) is a technology that is used to overcome the  
50 challenges associated with the high temperature processing of metallic parts [15]. In cold spray  
51 deposition, plastic deformation due to a high strain rate dynamic loading is utilized to form solid-  
52 state bonding between metallic powders [16]—the building blocks of the final parts. In cold  
53 spraying, powders are accelerated by a supersonic jet of compressed gas through a de Laval nozzle  
54 [15]. This is unlike other additive manufacturing processes, where powders are either laid down  
55 on a powder bed as is done in selective laser melting (SLM) and selective electron beam melting  
56 (SEBM) [17,18] or fed by a powder feeder at velocities up to 10 mm/s as is done in directed energy  
57 deposition (DED) [19–21]. Some Ti-6Al-4V porous structures have been fabricated by additive  
58 techniques such as SLM [22], SEBM [23–25], DED [26], and binderjet [27]. These studies have  
59 produced porous geometries by using a pattern of holes that occupies the build volume by a certain  
60 percentage or by printing a scaffold structure (a toolpath-based porosity). These porous parts have

61 high porosities ranging between 18% and 80% . To the authors' knowledge, making porous  
62 structures has never been studied using cold spray, and the high deposition rate of cold spray makes  
63 it a more efficient method of fabrication than the other methods discussed.

64 In cold spray, the powder impact velocity can be tuned to control the adhesion of metal  
65 powders [15]. If the powder impact velocity ( $v_i$ ) exceeds the critical impact velocity ( $v_{cr}$ ) and stays  
66 below the erosion velocity ( $v_{er}$ ), the majority of the powder will adhere to the surface and form a  
67 dense deposit [16,28]. The critical and erosion velocities are temperature-dependent and define the  
68 characteristic window of deposition on the velocity-temperature plane. In the present work, we  
69 intentionally worked in the subcritical velocity domain—a domain that has been avoided so far—  
70 to create porous metal deposits from Ti-6Al-4V alloy powders in a single step. The subcritical  
71 velocity domain is where the normalized particle impact velocity ( $\eta = \frac{v_i}{v_{cr}}$ ) is smaller than 1. The  
72 nozzle traverse speed was tuned to create uniform porosity throughout the thickness of the deposit.  
73 Deposits were analyzed with respect to porosity, surface roughness, liquid contact angle on  
74 substrate surface, and mechanical behavior. Moreover, the potential of post heat treatment to tune  
75 the mechanical properties of the porous deposits was demonstrated. Finally, these deposits were  
76 shown to support cell growth, which reveals that this method could be used to fabricate materials  
77 for biomedical implants and devices.

## 78 **2. Materials and Methods**

### 79 **2.1. Materials**

80 Ti-6Al-4V alloy powders (Advance Powders and Coatings, Boisbriand, Canada) with a  
81 Gaussian size distribution and particle sizes between 45 and 106  $\mu\text{m}$  were used in this study. The  
82 substrates on which the powders were printed are commercially pure Ti plates of 3-mm thickness.

### 83 **2.2. Supersonic particle deposition**

84       Supersonic particle deposition was performed using a CGT-Kinetic<sup>®</sup> 8000 high-pressure cold  
85 spray system. Titanium substrates were used as support structures. The key deposition parameters  
86 are process gas pressure, process gas temperature, and nozzle scan velocity. We studied four  
87 different deposition procedures by varying traverse speed and gas temperature. Specifically, slow  
88 (6 m/min) and fast (12 m/min) nozzle traverse speeds at two different preheated carrier gas  
89 temperatures (800 and 900 °C) were examined. Carrier gas pressure (40 bar), carrier gas (Nitrogen)  
90 and number of passes (5) were kept constant.

### 91       2.3. Subcritical deposition

92       To determine the experimental parameters for subcritical deposition, fluid dynamic  
93 calculations (finite volume two-phase flow analysis of gas and powder in the nozzle and in the free  
94 jet) available in a commercially available software from kinetic-spray-solutions (KSS GmbH,  
95 Buchholz, Germany) were used [29,30]. The contour plot of the normalized particle impact  
96 velocity ( $\eta$ ) as a function of gas pressure and temperature was used as a guideline to choose the  
97 experimental processing parameters. We kept the pressure constant at the maximum operating  
98 pressure of the device ( $P = 40$  bar) and chose gas temperatures to tune for  $\eta$  values close to but  
99 smaller than 1 to deposit in the subcritical domain. In several iterations, the gas temperatures  
100 fulfilling this requirement for the selected powder sizes were determined to range between 800  
101 and 900 °C. Powder sizes were selected to deviate from the optimum and be larger to allow for a  
102 better adjustment of the subcritical impact conditions. Using these deposition parameters ( $P = 40$   
103 bar and  $T = 800$  and  $900$  °C) and CFD calculations, we calculated the particle velocity and  
104 temperature upon impact for three different particle diameters as shown in Figure 1(a) (45, 75 and  
105 106  $\mu\text{m}$  corresponding to the minimum, median and maximum diameters in the particle size  
106 distribution range). For simplicity, we refer to these deposition conditions as T800 and T900 in

107 this paper, which correspond to the temperatures of the carrier gas. We also calculated the window  
108 of deposition for Ti-6Al-4V powders using the respective bulk material properties for the powder  
109 size regime used. During the experiments, substrates were preheated by scanning the substrates  
110 with a warm carrier gas (800 and 900 °C) for two consecutive passes to promote bonding at the  
111 interface. As a result, a stable growth of porous layers was achieved.

#### 112 2.4. Porosity and pore size measurements

113 The porosity of the deposits before and after the heat treatment was determined by a  
114 quantitative image analysis of the polished cross sections. The as-printed samples were prepared  
115 by mechanical polishing using several SiC sandpapers and diamond suspensions up to 1 μm,  
116 followed by 0.5 hour of polishing using a SiO<sub>2</sub> colloidal suspension. Binary images of the polished  
117 cross sections at the same magnification were used to calculate the pore (black voids) to the total  
118 surface area. The average and standard deviation of five measurements in different areas is  
119 reported. The porosity values reported in this study are a slight overestimate as some particles were  
120 lost during the grinding and polishing process, which is not accounted for in the image analysis.  
121 Therefore, the density of 3D printed samples was also measured using the Archimedes principal,  
122 and the density ratio was corroborated with the image analysis results. The porosities were  
123 determined with the aid of density calculation and hydrostatic weighing. The theoretical density  
124 of Ti used for this determination was 4.5 g/cm<sup>3</sup>. For each specimen, measurements were repeated  
125 three times, and the mean value is reported.

#### 126 2.5. Deposit powder size distribution

127 To understand the mechanism of the porous structure formation, we analyzed the powder  
128 size distribution in the deposits. The diameter of the adhered powders in 3D printed porous Ti-  
129 6Al-4V (T = 800 °C) was determined by measuring particle size in ImageJ. Three SEM images

130 were taken at 150X and the diameters of 100 particles per image were measured (a total of 300  
131 powder particles across the three images).

## 132 2.6. Compression testing

133 Quasi-static uniaxial compression tests were conducted on Gatan MTEST2000 Uniaxial  
134 Testing Stage. The samples were cut into cross sections of 2 cm × 2 cm, and the specimens were  
135 loaded parallel to their build direction. Three samples were tested for each condition. The average  
136 and the standard deviation of the stress-strain behavior were determined.

## 137 2.7. Heat treatment

138 Ti-6Al-4V is a two-phase alloy comprised of both  $\alpha$  and  $\beta$  phases at room temperature. The  
139  $\alpha$ -to- $\beta$  phase transformation ( $\beta$  transus temperature) occurs at  $\sim 970$  °C [31]. Heat treatments above  
140 (1050 °C) and below (840 °C) the  $\beta$ -transus temperature were performed in a tube furnace purged  
141 with Argon and at a heating rate of 10 °C/min. The specimens were maintained at the designated  
142 temperature for 2 hours followed by furnace cooling.

## 143 2.8. X-ray Diffraction

144 X ray diffraction (XRD) analyses were performed using  $\text{CuK}\alpha$  radiation on a PANalytical  
145 X'Pert Pro diffraction instrument operating at 45 kV and 40 mA between 30 and 60 deg ( $2\theta$ ) at a  
146 step size of 0.01 degrees and a counting time of 40 seconds per step.

## 147 2.9. Roughness

148 The InfiniteFocus (Alicona, Austria), an optical device for 3D surface measurements, was  
149 used to trace the surface profiles of as-received bulk material and 3D printed specimens using cold  
150 spray deposition. The operating principle of the device combines the small depth of focus with  
151 vertical scanning to provide topographical information from the variation of focus. The captured  
152 information from a  $5 \times 5$  cm<sup>2</sup> scanned area was reconstructed into a 3D topographical data set to

153 obtain the following surface roughness parameters: arithmetic average ( $S_a$ ), root mean square ( $S_q$ ),  
 154 maximum valley depth ( $S_v$ ), and maximum peak height ( $S_v$ ) [32].

155 2.10. Calculating contact temperature

156 The temperature at the impact zone was computed by calculating the temperature rise due  
 157 to heat released during impact. It was assumed that almost all kinetic energy is converted to heat  
 158 and that the heat is released in a fraction of particle height ( $\beta h_p$ ), where  $\beta$  is the deformation  
 159 localization coefficient, and  $h_p$  is the particle height after impact. This may be taken as a  
 160 representative estimate for the actual temperature for a relative comparison of the results for  
 161 different impact parameters. The increase of the contact temperature ( $T_c$ ) due to heat release during  
 162 the impact at the contact plane, in the one-dimensional approximation, was calculated as follows  
 163 [33,34]:

$$164 \quad T_c(t) = \frac{v_p^3 t_c}{8c\beta\varepsilon_p d_p} \int_0^1 \operatorname{erf}\left(\frac{d_p \beta (1-\varepsilon_p)}{\sqrt{4\alpha t_c (1-\tau)}}\right) d\tau \quad \text{Eq. 1}$$

165 where  $v_p$  is the powder impact velocity,  $c$  is coefficient of specific heat,  $d_p$  is particle diameter,  
 166  $\varepsilon_p$  is plastic strain,  $\alpha$  is thermal diffusivity,  $t_c$  is contact time, and  $\tau = \frac{t}{t_c}$  is the relative time. The  
 167 specific values for constants are tabulated in Table I.

168 Table I: Constant values for calculating contact temperature at impact zone according to Equation 1  
 169 [34,35].

Constants		
C (J/Kg*K)	Specific heat	526
$\beta$	Deformation localization	0.1
K (W/mK)	Conductivity	7.2
$\rho$ (Kg/m <sup>3</sup> )	Density	4430
$T_c^0$ (K)	Initial contact temperature	300

$T_{melt}(K)$	Melting temperature	1900
$H_p$ (MPa)	Powder hardness	3423
Definitions		
$t_c$ (s)	Contact time	$t_c = \frac{2\varepsilon_p d_p}{v}$
$\varepsilon_p$	Plastic strain	$\varepsilon_p = \exp(-0.6 \frac{H_p}{\rho_p v_p^2})$
$h_p$	Particle height after impact	
$\alpha$ (m <sup>2</sup> /s)	Thermal diffusivity	$\alpha = \frac{k}{c\rho}$
$\tau$	Relative time	$\tau = \frac{t}{t_c}$

170

171 Dimensional analysis shows that the plastic strain variation during supersonic impact is

172 dependent on the dimensionless parameter  $\frac{H_p}{\rho_p v_p^2}$ . The expression relating plastic strain to this

173 dimensionless parameter ( $\varepsilon_p = \exp(C \frac{H_p}{\rho_p v_p^2})$ ) has the correct asymptotic values i.e. plastic strain

174 approaches 1 as impact velocity goes to infinity, and plastic strain approaches 0 as particle impact

175 velocity approaches 0 [34]. The constant  $C$  for the analytical expression was calculated based on

176 a series of finite element simulations at different impact velocities (600 to 1000 m/s in 100 m/s

177 increments) as described in the next section, which turns out to be equal to 0.6.

178 2.11. Finite element model

179 For calculating the contact temperature, the value of plastic strain in powders during impact

180 is required (according to Eq. 1). An axisymmetric dynamic explicit model was created in

181 ABAQUS 6.14 to determine the plastic strain. The impact of a single Ti-6Al-4V particle (D = 50

182  $\mu\text{m}$ ) with rigid substrates was modeled. The Johnson-Cook constitutive equation (Eq. 2), which



183 accounts for strain hardening, strain rate hardening, and thermal softening, describes the powder  
 184 deformation behavior.

$$185 \quad \sigma = [A + B\varepsilon_p^n] \left[ 1 + c \frac{\dot{\varepsilon}_p}{\dot{\varepsilon}_{p0}} \right] \left[ 1 - \left( \frac{T-T_0}{T_m-T_0} \right)^m \right] \quad \text{Eq. 2}$$

186 where  $A$ ,  $B$ ,  $n$ ,  $c$  and  $m$  are material constants and are measured by experiments,  $\varepsilon_p$  and  $\dot{\varepsilon}_p$  are the  
 187 equivalent plastic strain and equivalent plastic deformation rates, and  $T_0$  is the reference  
 188 temperature. Values for constants are reported in Table II.

189 Table II: Ti-6Al-4V properties for finite element simulation [35].

Elastic	Elastic Modulus	E (GPa)	113.8
	Poisson ratio	$\nu$	0.342
Plastic	Johnson Cook constants	A (MPa)	782.7
		B (MPa)	498.4
		n	0.28
		c	0.028
		m	1
	Reference Temperature	$T_0$ (K)	300
	Reference plastic strain rate	$\dot{\varepsilon}_{p0}$	$1 \times 10^5$

190

## 191 2.12. Cell Line and Culture Methods

192 Pre-osteoblast MC3T3-E1 Subclone 4 cells of passage number less than P7 were grown in  
 193 standard culture conditions (37°C, 5% CO<sub>2</sub>) using Alpha Minimum Essential Medium (Life  
 194 Technologies, Grand Island, NY) supplemented with 10% fetal bovine serum, 1% penicillin, and  
 195 1% streptomycin. After trypsinization, 10,000 cells/cm<sup>2</sup> were seeded and cultured on titanium

196 support materials and porous Ti-6Al-4V for seven days in 12-well tissue culture dishes. Growth  
197 media was exchanged every 2-3 days. Four replicates were performed on each substrate to assess  
198 the biocompatibility and integration of cells into porous substrates. Biocompatibility and  
199 integration of cells into the porous Ti-6Al-4V was inspected using confocal laser scanning  
200 microscopy and scanning electron microscopy.

### 201 2.13. Imaging and Image Analysis for Biocompatibility Studies

202 For confocal laser scanning microscopy experiments, cells were stained with 2  $\mu$ M Calcein  
203 AM, and 4  $\mu$ M Ethidium Homodimer-1 from the LIVE/DEAD Viability/Cytotoxicity Kit, for  
204 mammalian cells (Molecular Probes, Eugene, OR). Nuclei were labeled using one to two drops/mL  
205 NucBlue Live Cell Stain ReadyProbes reagent (Molecular Probes, Eugene, OR). 3D image  
206 volumes of cells were obtained using a Nikon A1 Confocal Laser Scanning Microscope (Nikon,  
207 Melville, NY) using a 4x, NA 0.2 objective, and a 20x, NA 0.75 objective. Four image volumes  
208 were captured at each magnification for each sample. Representative LIVE/DEAD images were  
209 presented for each growth condition. The depth that cells grew into the porous deposit was  
210 determined by imaging from the coverslip into the sample until stained cells could no longer be  
211 observed with the 4x objective. The depth was then computed by multiplying the z-step size (13  
212  $\mu$ m) by the number of slices into the sample where cells were observed; the average depth and  
213 standard error of the mean are reported. Fluorescence images were also shown to demonstrate how  
214 cells were growing on and between the metal powders that create the porous deposit.

215 Scanning electron microscopy (SEM) was performed to determine the morphology of the  
216 cells on and within the porous Ti-6Al-4V. To prepare the samples for SEM, cells grown on the Ti-  
217 6Al-4V porous structure were first fixed in 2.5% glutaraldehyde for one hour, followed by post  
218 fixation in 1% osmium tetroxide for one hour. This procedure was followed by ethanol

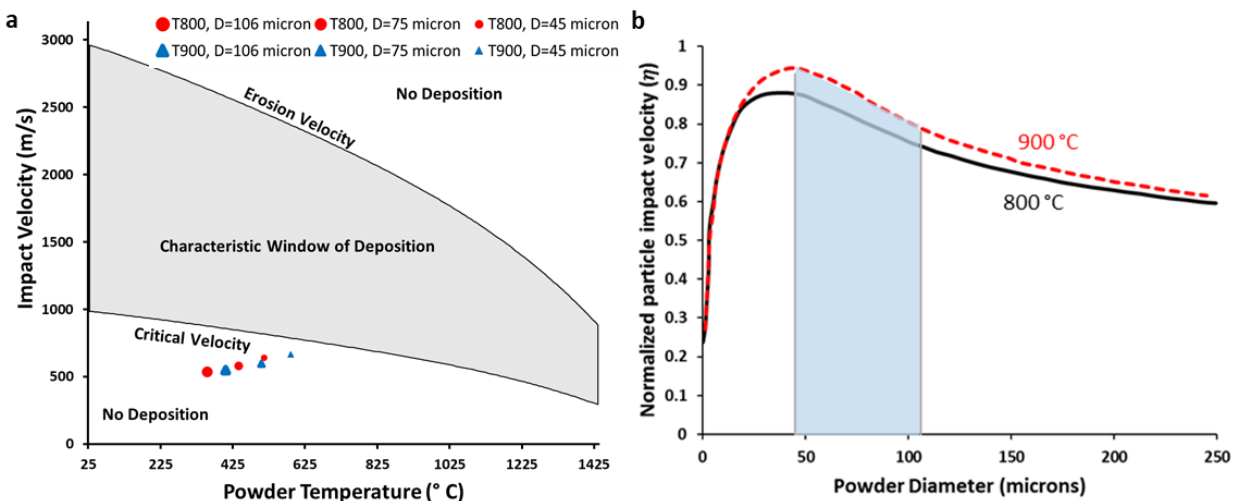
219 dehydration, where cells were treated with increasing concentrations of ethanol (30%, 50% 70%  
220 90% and 100%) for 15 minutes each.

221

### 222 3. Results and Discussion

223 To ensure that the deposition parameters for our 3D printed deposits remain below the  
224 window of deposition, we created and referred to an experimental parameter selection map by  
225 performing fluid dynamics calculations as was described in section 2.3. As shown in Figure 1(a),  
226 critical and erosion velocities drop when the powder temperature increases. In addition, all the  
227 processing conditions for the powder under investigation lie beneath the characteristic window of  
228 deposition. Figure 1(b) shows the normalized particle impact velocity,  $\eta$ , as a function of powder  
229 diameter, which illustrates that a smaller particle diameter results in a higher impact velocity for  
230 the range of interest (shaded in grey). Additionally, the plot shows that a higher temperature is  
231 associated with higher values for  $\eta$ .

232



233

234 **Figure 1:** Supersonic powder deposition and determination of deposition parameters. (a) Calculated impact  
235 conditions for parameter sets used to manufacture porous deposits with carrier gas temperature  $T = 800\text{ }^{\circ}\text{C}$

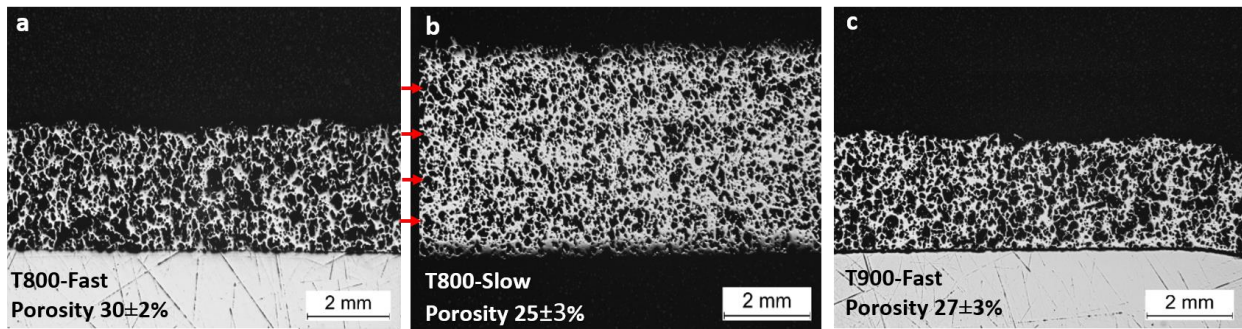
236 (red circles) and  $T = 900\text{ }^{\circ}\text{C}$  (blue triangles) at  $P_{\text{gas}} = 40$  bars. Symbol size is indicative of particle size, and  
237 thresholds for deposit formation in terms of critical velocity. The powder impact conditions are intentionally  
238 outside of the calculated window of deposition used to print porous metallic deposits. (b) Normalized  
239 particle impact velocity ( $\eta$ ) as a function of particle diameter with the powder size distribution used in our  
240 experiments (45-105  $\mu\text{m}$ ) shaded in blue.

241

242

243 Deposition using a nozzle traverse speed of 12 m/min (fast deposition) with a carrier gas  
244 temperature of  $800\text{ }^{\circ}\text{C}$  ( $\eta$  between 0.74 and 0.87) corresponds to a deposited thickness-per-path  
245 ratio of 0.5 mm and results in  $30\pm 2\%$  porosity with a uniform distribution across the thickness as  
246 illustrated in Figure (a). We studied the effect of nozzle traverse speed on deposition kinetics by  
247 reducing the nozzle traverse speed to half (6 m/min), which corresponds to a deposited thickness  
248 per pass ratio of 1 mm (slow deposition). Slow deposition resulted in deposits with  $25\pm 3\%$   
249 porosity. A representative cross section of deposits fabricated with slow deposition is shown in  
250 Figure (b). Comparing Figure (a) and (b) shows that slowing the nozzle traverse speed decreases  
251 porosity. Decreasing the nozzle traverse speed increases the local surface temperature of the pre-  
252 deposited material due to a longer gas-deposit interaction, which enhances the deposit quality [36].  
253 This surface temperature effect on porosity is further confirmed by repeating the fast deposition  
254 experiment at a higher temperature ( $900\text{ }^{\circ}\text{C}$ ). When fast deposition was performed with a carrier  
255 gas temperature of  $900\text{ }^{\circ}\text{C}$ , materials were fabricated with buildup thickness per pass similar to  
256 fast deposition with a carrier gas temperature of  $800\text{ }^{\circ}\text{C}$  but with lower porosities ( $27\pm 3\%$ , Figure  
257 (c)). Therefore, a variation in deposit surface temperature due to differences in nozzle traverse  
258 speed can cause modifications in the mesostructure at the interface between each deposition pass  
259 (showing uniform porosity for fast depositions and dense-porous layered structure in the slow  
260 deposition). The results show that the porosity of the deposit ( $\rho$ ) can be controlled by  $\eta$  and nozzle  
261 traverse speed ( $\rho = f(V_N, \eta)$ ), where porosity increases as  $V_N$  increases and as  $\eta$  decreases [37].

262  $\eta$  is a function of the deposition parameters (i.e. gas pressure, temperature, powder diameter).  
 263 Deposition parameters are summarized in Table III. Porosity measurement using Archimedes  
 264 principal is also reported in the table, which shows slightly lower values with respect to the image  
 265 analysis results. Results discussed beyond this point are those of printed deposits with  $30\pm 2\%$   
 266 porosity (fast deposition with  $800\text{ }^\circ\text{C}$  carrier gas temperature) unless noted otherwise.



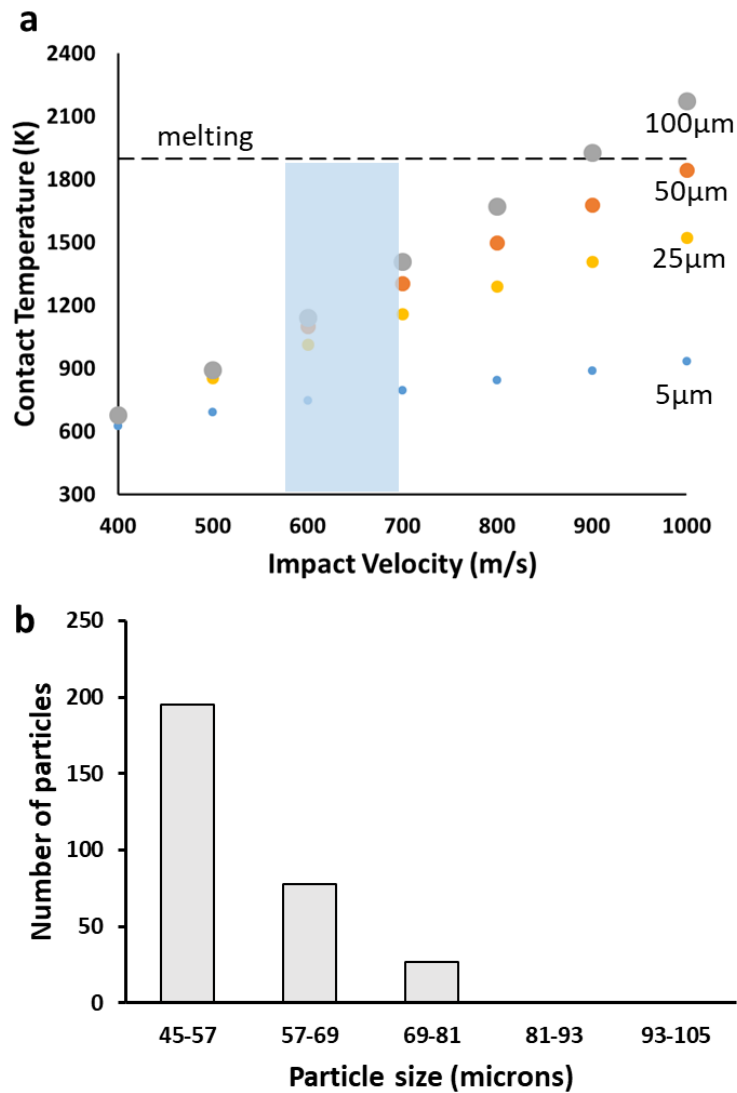
267  
 268 **Figure 2:** Optical micrograph of cross sections of materials printed using (a) fast deposition, and (b) slow  
 269 deposition (the red arrows on the left side of panel b show the interfaces between different passes). (c)  
 270 Cross section optical micrograph of fast deposition at carrier gas temperature  $T=900\text{ }^\circ\text{C}$  showing similar  
 271 structure to fast deposition at carrier gas temperature  $T=800\text{ }^\circ\text{C}$  but with less porosity (porosity  $27\pm 3$ ).

272 Table III: Experimental conditions used for cold spray deposition of titanium powders. Process gas  
 273 pressure (40 bar), process gas (nitrogen) and number of passes (5) were kept constant, while temperature  
 274 and scan velocity were varied. Porosity from image analysis and Archimedes' principle are reported in the  
 275 last two columns, respectively.

Group name	Process gas temperature ( $^\circ\text{C}$ )	Scan velocity (m/min)	$\eta$ for $D = 75\text{ }\mu\text{m}$	Porosity (Optical method)	Porosity (Archimedes principle)
T800-slow	800	6	0.79	$25\pm 3\%$	$22\pm 0.07\%$
T800-fast	800	12	0.79	$30\pm 2\%$	$27\pm 0.1\%$
T900-fast	900	12	0.84	$27\pm 3\%$	$24\pm 0.08\%$

276  
 277 High velocity impact during cold spray deposition can cause inhomogeneous deformation  
 278 and localized heating of the interacting surfaces. To study the possible influences of particle sizes,  
 279 the contact temperature was analyzed by the temperature rise at the impact zone as described in

280 section 2.10. Figure 3(a) shows a plot of powder temperature at the contact plane versus impact  
 281 velocity for different powder diameters from 5  $\mu\text{m}$  to 100  $\mu\text{m}$  at the end of contact ( $t = t_c$ ).  
 282 Velocities used in the present experimental work ranged from 580 m/s to 700 m/s considering the  
 283 heterogeneity of the powder sizes, as depicted by the shaded area. As shown in Figure 3(a), the  
 284 contact temperatures for different powder sizes were found below the material's melting point and  
 285 to increase with particle size and impact velocity for the full range of particle impact velocities  
 286 (590-700 mm/s) and diameters (5-100  $\mu\text{m}$ ).



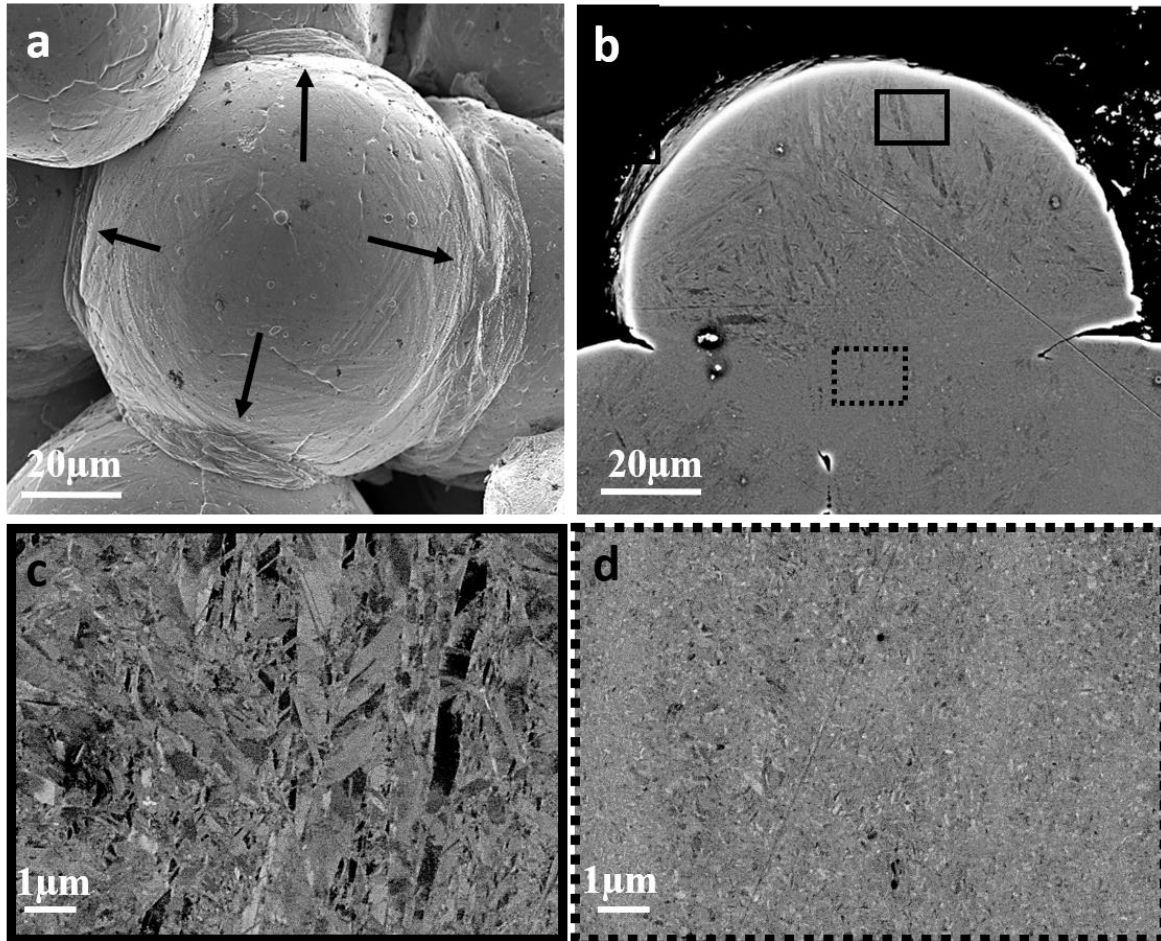
288 **Figure 3:** (a) Contact temperature as a function of particle impact velocity and diameter, where contact  
289 temperature increases with particle size (shaded area shows the range of velocities used experimentally to  
290 fabricate porous metal deposits). (b) Particle size distribution in 3D printed porous Ti-6Al-4V (fast  
291 deposition at carrier gas temperature 800 °C) after deposition.

292

293 Analyzing the powder particle size distribution within our 3D printed porous Ti-6Al-4V  
294 deposits reveals that the majority of powders that adhered to the substrate are in a size range  
295 between 45-57  $\mu\text{m}$ , and the distribution of powders was heavily biased toward smaller powder  
296 sizes. The original powder had a Gaussian size distribution with diameters between 45 and 105  
297  $\mu\text{m}$ . However, in the 3D printed porous Ti-6Al-4V deposit, 65% of powders were in a range  
298 between 45-57  $\mu\text{m}$ , 26% were between 57-69  $\mu\text{m}$ , and 9% were between 69-81  $\mu\text{m}$  (Figure 3(b)).  
299 The maximum powder size in the consolidated deposit was 80  $\mu\text{m}$ , whose value of  $\eta$  was 0.8  
300 according to Figure 1 (b)). This implies that powders larger than 80  $\mu\text{m}$  were not bonded during  
301 deposition. This finding illustrates that the effect of decreased impact velocity due to increased  
302 particle size is more significant than that of the increased contact temperature associated with  
303 larger particles. Namely, larger particles do not adhere to the surface despite their higher contact  
304 temperature because of the lower  $\eta$  as shown in Figure 1(b). We note that the estimated upper  
305 particle size of 80  $\mu\text{m}$  is conservative because impact induced deformation can artificially  
306 “increase” the powder size.

307 Scanning electron micrographs of the top view and cross section of powders after impact  
308 reveal the lateral flow of the material at all points of contact (shown by arrows in Figure 4(a)).  
309 This is due to localized deformation at the high impact velocity and is important in washing out  
310 the broken surface oxides from the contact zone and allowing for direct metallic bonds in addition  
311 to mechanical interlocking at the interface [15]. The cross section of a powder after impact shows  
312 an extensive grain refinement in the impact region (Figure 4(d)) with respect to the undeformed

313 region (Figure 4(c)). This shows that the 3D printed constructs have spatial gradients in grain  
314 microstructure within each deposit particle due to the dynamic loading that powders experience  
315 during impact.



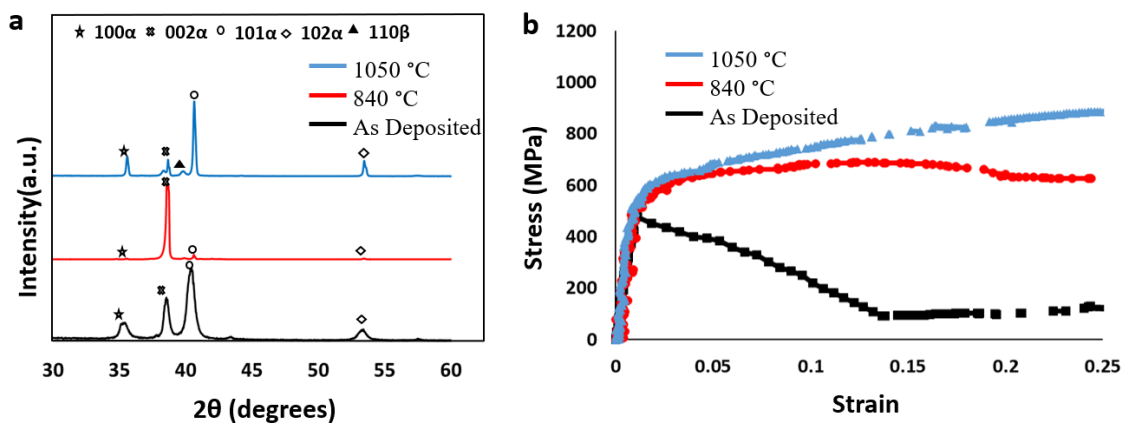
316  
317 **Figure 4:** Scanning electron micrographs of 3D printed Ti-6Al-4V parts. (a) Top view of a powder particle  
318 after impact. The arrows show lateral material flow at the periphery of the powder upon impact. (b) Cross  
319 section of powder after impact. (c) Magnified view of microstructure in undeformed region of powder  
320 depicted in (b). (d) Magnified view of refined microstructure at impact zone of powder depicted in (b).  
321 Frame pattern indicates the corresponding area in in the cross-section overview.

322

323 To determine how diffusion kinetics especially at the interface between powder particles  
324 influence the mechanics of 3D printed porous deposits, we performed heat treatments at 840 °C  
325 and 1050 °C for 1 hour (referred to as HT840 and HT1050 in this paper). These treatments are



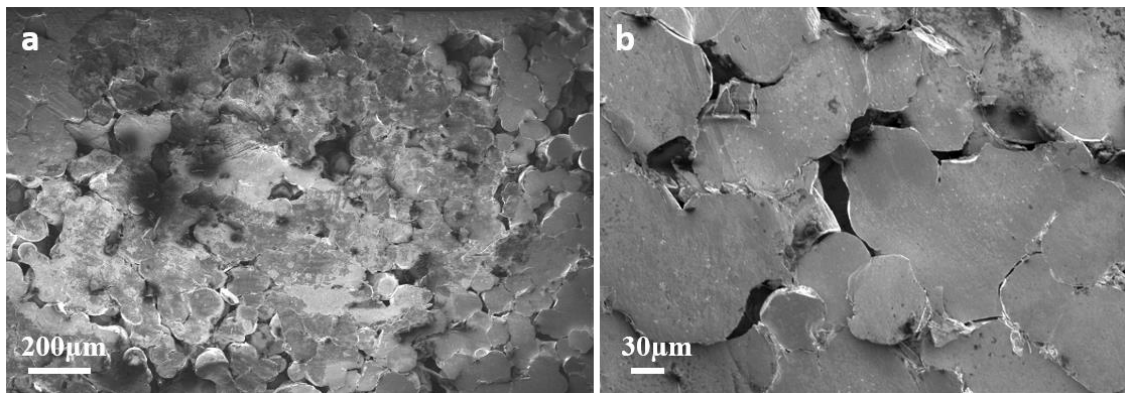
326 below and above the beta transus temperature (i.e. the lowest temperature at which a 100% beta  
 327 phase can exist;  $\sim 970$  °C for Ti-6Al-4V [31]). Porosities of the heat-treated samples are  $38 \pm 4\%$   
 328 and  $33 \pm 2\%$  for 840 °C and 1050 °C, respectively. The optical micrographs of the heat-treated  
 329 samples are shown in Supplemental Figure S1. The slight increase in porosity compared to that of  
 330 as-printed samples can be explained by the coalescence of small pores and/or pore rearrangement  
 331 as a result of sintering [38]. X-ray diffraction measurements reveal changes in microstructure and  
 332 phase structure of the material after heat treatment. Specifically, peaks in X-ray diffraction patterns  
 333 become sharper after heat treatment, which corresponds to the healing of defects from deformation  
 334 by recrystallization and grain growth (Figure 5(a)). There is also a peak at  $2\theta = 35.5^\circ$  after heat  
 335 treatment at 1050 °C, indicating some remaining beta phase after the heat treatment above the beta  
 336 transus temperature. The peak intensities of alpha titanium indicate a slight texture of the as  
 337 deposited material, which could be attributed to the degree deformation of particles upon impact.  
 338 This texture appears more pronounced after annealing, particularly at heat treatment below beta  
 339 transus temperature.



340  
 341 **Figure 5:** Characterization of the 3D printed Ti-6Al-4V deposits in as-deposited condition and after heat  
 342 treatment. (a) X ray diffraction (XRD) pattern of as deposited and annealed samples. (b) Stress-strain  
 343 behavior of as-deposited and annealed samples under compression loading.

344

345 The stress-strain behavior of as-deposited porous structures under compression shows a  
346 linear regime followed by a sudden decrease in the stress-strain curve and finally a densification  
347 regime (Figure 5(b)). At low stress level, the deformation is homogenous throughout the specimen  
348 with an initial stress/strain ratio equal to  $51.7\pm 3.2$  GPa. The sample yields at  $535\pm 35$  MPa. Above  
349 a critical stress, sudden drop in stress occurs that corresponds to fracture at interparticle boundaries  
350 as shown by the SEM images in Figure 6.



351

352 **Figure 6:** Post mortem fracture analysis of as deposited samples after compression loading showing  
353 fracture at interparticle boundaries on the (a) milli scale and (b) microscale.  
354

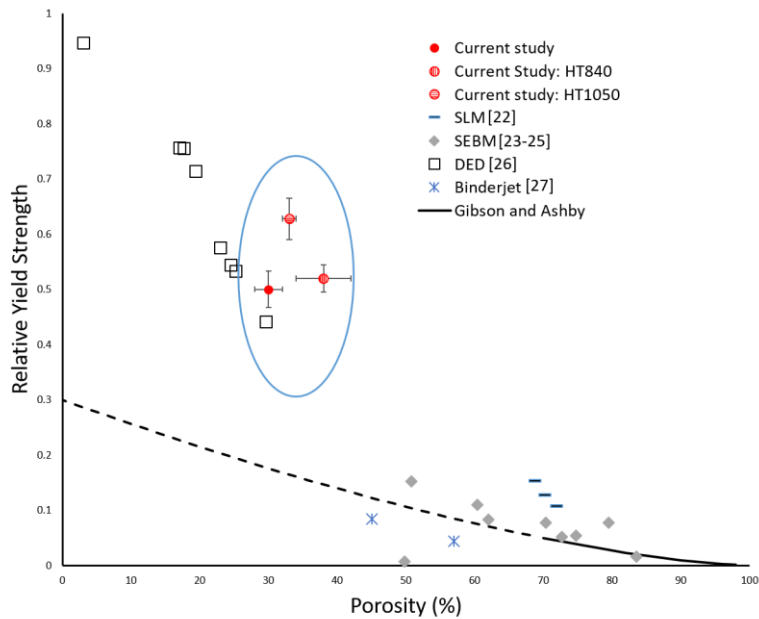
355 In heat-treated samples (840 °C, 1050 °C), the stress-strain behavior under compression  
356 has a linear regime, followed by a steady increase of stress as strain is increased (Figure (b)). The  
357 stress-strain behavior of the heat-treated sample at the elevated temperature (1050 °C) shows a  
358 higher compressive yield strength and maximum stress as compared to the heat-treated sample at  
359 lower temperature (840 °C). The apparent initial slopes after heat treatments both above and below  
360 the beta transus temperature are comparable to that in the as-deposited sample ( $51.7\pm 3.2$  GPa,  
361  $42.4\pm 2.6$  GPa, and  $55.1\pm 2.4$  GPa for as-deposited, HT840, and HT1050, respectively). However,  
362 the compressive yield stresses of both heat treated samples are higher than that of the as-deposited  
363 ( $535\pm 35$  MPa,  $556\pm 26$  MPa , and  $672\pm 40$  MPa for as-deposited, HT840, and HT1050,

364 respectively). After heat treatments, the interparticle contact area may grow and become  
365 increasingly stronger due to interparticle diffusion. This can compensate for the typical softening  
366 upon coarsening of the microstructure at higher temperatures. Furthermore, coarser  
367 microstructures are known to be less brittle than fine grained material and therefore are more crack  
368 resistant. Thus, failure of contact zones becomes less likely during deformation of annealed  
369 samples and leads to the observed steady increase in average strength until strain is increased  
370 beyond 10% or more. This shows that heat treatment can serve as a new design parameter to control  
371 and improve the stress-strain behavior of porous deposits printed using cold spray, which is  
372 valuable for biomedical, structural and energy absorption applications. Annealing conditions for  
373 designing a foam with a particular stress-strain behavior can be optimized through tuning the  
374 competing influences between stronger interparticle bonding and lower recrystallization softening  
375 for different material applications.

376         When compared to porous Ti-6Al-4V structures manufactured by other additive  
377 manufacturing methods such as SLM [22], SEBM [23–25], DED [26] and binderjet [27], the  
378 relative compressive yield strength values of this study are higher. Here, the relative compressive  
379 yield strength refers to the ratio of the compressive yield strength of the porous structure compared  
380 to that of a fully dense part (1070 MPa). These values are plotted in Figure and listed in Table IV  
381 (similar porosities circled in the Figure). The expected relative compressive yield strength values  
382 from the Gibson-Ashby model are plotted for comparison. The model relates the compressive yield  
383 strength with relative density and scales with  $0.3(\textit{relative density})^{1.5}$ , though this model only  
384 applies to porosities larger than 70% shown by a solid line in Figure 7 [39]. Indeed, additive  
385 manufactured samples seems to follow the Ashby model up until about 40% porosity, beyond  
386 which a large deviation from the Gibson-Ashby model occurs. This can be explained by the

387 different deformation modes in high and low porosity ranges that result in a jump in relative  
 388 compressive yield strengths; in higher porosity structures, the primary mode of deformation in  
 389 compression is buckling of the cell walls, whereas in lower porosity structures, the deformation is  
 390 largely shearing or yielding [39]. This shift in primary deformation mode occurs as porosity  
 391 decreases because the cell walls become too stocky and short to buckle. The higher relative  
 392 apparent compressive yield strength of our deposit can be attributed to significant work hardening  
 393 induced by severe plastic deformation during impact which can be a driving force for heterogenous  
 394 recrystallization of fine grains at the impact zone after heat treatment cycles.

395



396

397 **Figure 7:** Relative compressive yield strength vs porosity of porous titanium structures fabricated by cold  
 398 spray as well as SLM, SEBM, DED and binderjet additive manufacturing technologies. Gibson-Ashby  
 399 model is plotted. The data points with similar porosity to our samples are circled in the figure.

400

401 Table IV: Comparison of compressive yield strengths of Ti-6Al-4V porous structures

AM	Porosity (%)	Mechanical properties	Reference
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		Compressive yield strength (MPa)	Relative compressive yield strength	
Cold Spray	30	535	0.500	Current study
	38	556	0.520	
	33	672	0.628	
SLM	70.2	136	0.127	[22]
	71.9	115	0.107	
	68.7	164	0.153	
EBM	72.7	55	0.051	[23]
	50.8	163	0.152	[24]
	60.4	117	0.109	
	70.3	83	0.078	
	49.8	7.3	0.007	
	62	88	0.082	[25]
	74.7	57	0.053	
	79.5	82	0.077	
	83.5	17	0.016	
DED	29.6	471.9	0.441	[26]
	25.2	571	0.534	
	24.4	582.6	0.545	
	23	616.1	0.576	
	19.3	764.2	0.714	
	17.6	807.9	0.755	
	17	809.2	0.756	
	3	1012.7	0.946	
Binderjet	45	90	0.084	[27]
	57	47	0.043	

402  
403

404 To evaluate the suitability of porous Ti-6Al-4V for biomedical applications, surface  
405 roughness, contact angle measurement and biocompatibility studies are performed. The arithmetic  
406 mean surface roughness of our 3D printed titanium alloy is 37  $\mu\text{m}$ , which is more than 6 times the  
407 surface roughness of the as-received substrate. The surface roughness falls into the macro  
408 roughness regime (roughness  $>10 \mu\text{m}$ ), which is important for long-term mechanical stability and  
409 biomedical applications related to primary bone implant fixation [40]. Roughness parameters  
410 (arithmetic average, root mean square, maximum valley depth and maximum peak height) are

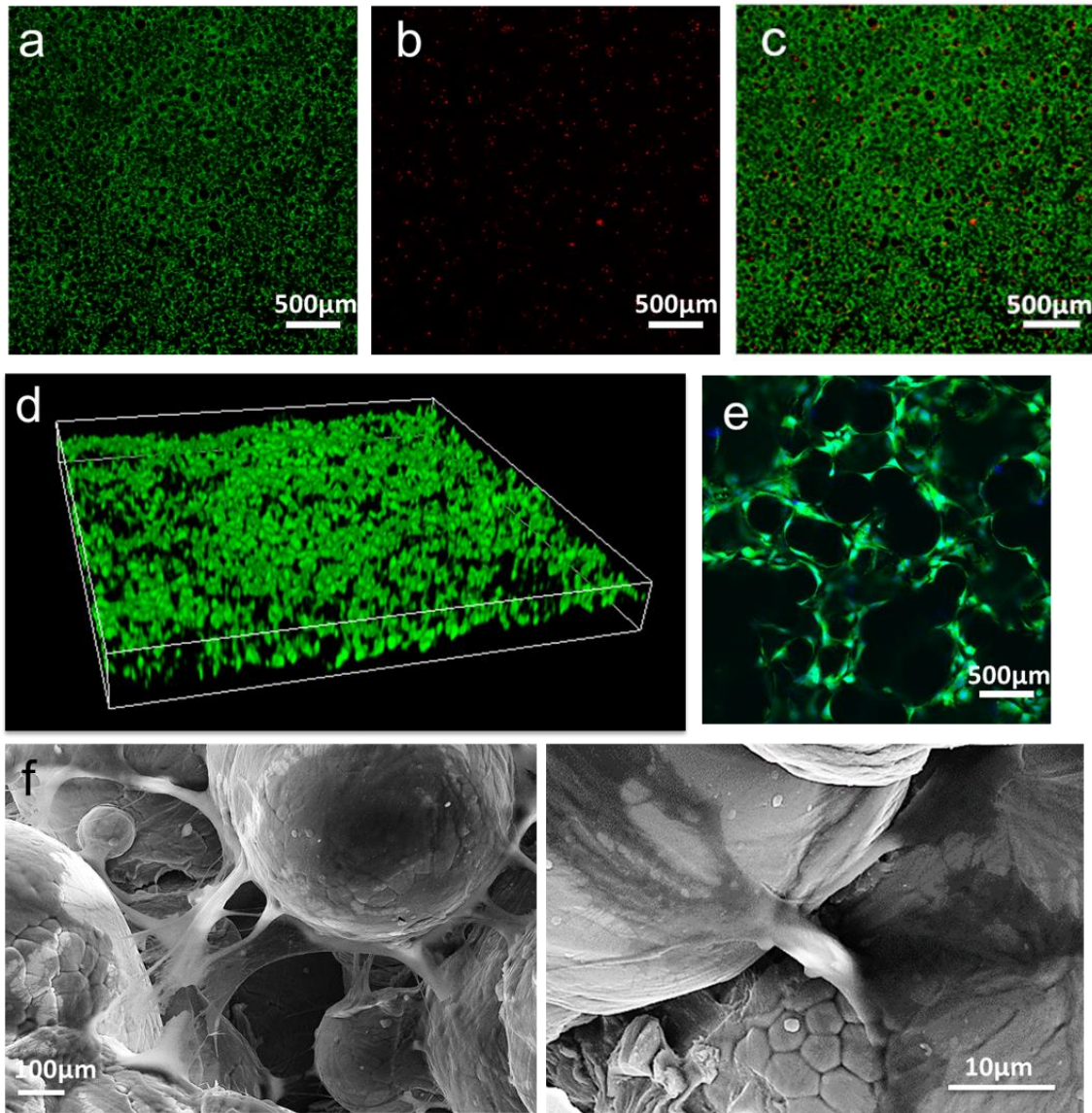
411 tabulated in Table V. Contact angle measurement against distilled water is not possible on these  
 412 samples, as the drop is absorbed instantaneously into the pores of the surface (Supplementary  
 413 Video S1). This confirms the open-cell structure of the 3D printed titanium alloy. Open cell  
 414 structures are particularly important for biomedical applications of porous materials, as they allow  
 415 for the transport of nutrients, oxygen, and waste products to and from cells adhering to the porous  
 416 substrates.

417 **Table V:** Surface roughness parameters of bulk titanium substrates and 3D printed Ti-6Al-4V deposits. \*  
 418 Parameters are according to ISO 4278 geometrical product specification.  $S_a$ : Arithmetic average,  $S_q$ :  
 419 Root mean square,  $S_v$ : Maximum valley depth,  $S_p$ : Maximum peak height

Treatment	$S_a(\mu\text{m})^*$	$S_q(\mu\text{m})$	$S_v(\mu\text{m})$	$S_p(\mu\text{m})$
Substrate	6	8	54	68
T800-Fast	37	47	231	204
T900-Fast	36	46	209	212

420  
 421  
 422 Murine preosteoblast cells (MC3T3-E1 SC4,  $P < 7$ ) are found to be biocompatible with cold  
 423 spray fabricated porous Ti-6Al-4V deposits. Preosteoblast cells adhere to the surface of the porous  
 424 Ti-6Al-4V and maintain viability over the course of seven days as demonstrated by predominantly  
 425 live cells and few dead cells being present after seven days of growth (Figure 8 (a)-(c)). The porous  
 426 nature of the deposit's 3D architecture allowed cells to integrate into the first  $275 \pm 12 \mu\text{m}$  of the  
 427 porous Ti-6Al-4V, as shown in Figure 8(d). Cells grew directly on the surface of the particles on  
 428 the surface as well as between them as evidenced by confocal microscopy (Figure 8 (e)) and  
 429 corroborated by SEM imaging (Figure (f),(g)). Pores at the surface have sizes in the range of 80 to  
 430  $320 \mu\text{m}$ , which is within the size range shown to be optimal for bone ingrowth (50 to  $800 \mu\text{m}$ )  
 431 [17]. These biocompatibility experiments demonstrate that pre-osteoblasts are capable of  
 432 integrating into the interstices of the pores of the cold spray fabricated titanium alloy, while

433 maintaining their viability, which reveals the utility of these materials for cellular ingrowth, an  
434 essential characteristic of successful bone scaffolds [41].



435  
436 **Figure 8:** Biocompatibility of murine preosteoblasts with Ti-6Al-4V metallic foam. (a-c) Representative  
437 LIVE (green, a)/DEAD (red, b) and Merged (c) confocal microscopy images of cells that grew within the  
438 first 275 µm of a porous titanium substrate. Images are projection images of the average intensities from  
439 confocal microscopy image volumes of 3.2 mm x 3.2 mm x 275 µm. (d) Rendering of a 3D image volume  
440 of preosteoblasts that grew 275 µm into the Ti-6Al-4V porous deposit. (e) Murine preosteoblasts (live cells-  
441 green, cell nuclei-blue) growing around and between titanium powder. Ti-6Al-4V particles are the spherical  
442 black voids within the image. (f) SEM images of cells on surfaces of 3D printed Ti-6Al-4V powders. (g)  
443 Magnified view of cells on 3D printed porous titanium.  
444  
445

446 Beyond biomedical applications, the one-step nature of the process and the high deposition  
447 rates of cold spray ( $10 \text{ cm}^3/\text{min}$  as opposed to  $10 \text{ cm}^3/\text{hour}$  in powder bed metal additive  
448 manufacturing [17,42]) make the method attractive for the fabrication of cellular metals with large-  
449 scale industrial applications in construction, transportation, and energy. Additionally, the one-step  
450 subcritical cold spray deposition can be adopted to deposit cellular structures using a wide range  
451 of metallic materials that are already in use in cold spray processing. In this work, we printed  
452 simple rectangular geometries to understand the deposition kinetics and mechanical properties of  
453 these structures. However, this can be easily adopted to make 3D objects by integrating the  
454 supersonic nozzle in cold spray with a commercially available robot as is already achieved by  
455 companies such as Impact Innovation [43], NRC Canada [44] and Speed3D [45].

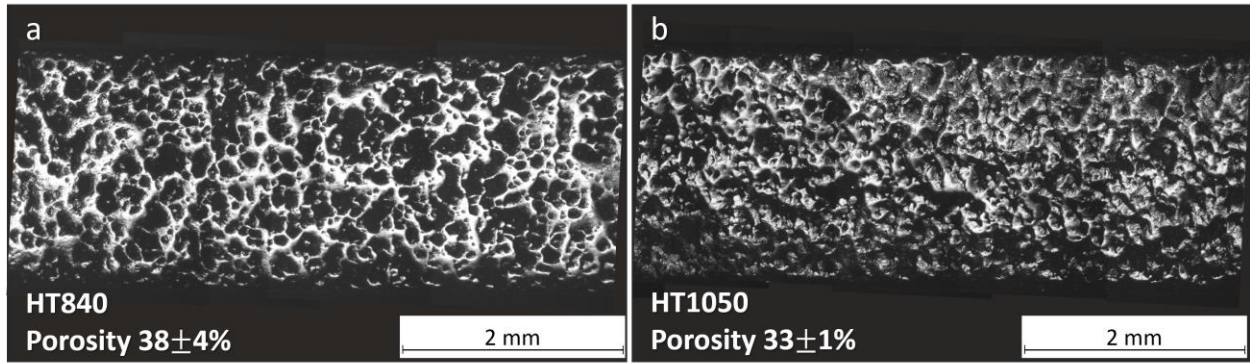
## 456 **4. Conclusion**

457 Subcritical cold spray is demonstrated to enable one-step fabrication of porous Ti-6Al-4V  
458 structures printed by accelerating powders to supersonic impact velocities. Nozzle traverse speed  
459 is tuned to control the distribution of porosity across the deposit thickness. With specific deposition  
460 parameters ( $V_N = 12 \text{ m/min}$ ,  $\eta \sim 0.8$ ,  $P = 40 \text{ bar}$ ,  $T = 800 \text{ }^\circ\text{C}$ ), a uniform porosity of  $30 \pm 2\%$  is  
461 obtained. The density of the deposit is demonstrated to be a function of nozzle traverse speed and  
462 normalized powder impact velocity ( $\eta$ ). The apparent Young's modulus of the 3D printed titanium  
463 alloy ( $51.7 \pm 3.2 \text{ GPa}$ ) is similar while the compressive yield strength is up to 42% higher than that  
464 of the porous structures manufactured by other additive manufacturing methods with the same  
465 porosity. After heat treatment, the elastic modulus does not change significantly, but the average  
466 strength shows a steady increase until plastic strain is increased beyond 10% or more. Finally, the  
467 printed porous metal deposits prove as biocompatible, demonstrating the utility of 3D solid-state



468 cold spray printing as a potential manufacturing method for producing biomedical implant  
469 materials.

470 **Appendix:**



472 **Figure A.1:** Optical micrograph of cross sections of heat-treated Ti-6Al-4V porous samples at (a) 840 °C  
473 (porosity 38±4%) and (b) at 1050 °C (porosity 33±1%).

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593

594 **Author Contributions** A.M., F.G., H.A. and M.D. conceived the ideas and designed the project. M.D.,  
595 T.K, M.G, and A.M. supervised the project, A. M. and A.W. performed mechanical characterizations.  
596 A.M. and E.J.S. designed and conducted biocompatibility studies. A.M., E.J.S., and M.D. wrote the  
597 manuscript with input from all authors.

598  
599 **Competing Interests**  
600 The authors declare no competing financial interests.  
601  
602

603 **Figure captions:**

604 **Figure 2:** Supersonic powder deposition and determination of deposition parameters. (a) Calculated impact  
605 conditions for parameter sets used to manufacture porous deposits with carrier gas temperature  $T = 800\text{ }^{\circ}\text{C}$   
606 (red circles) and  $T = 900\text{ }^{\circ}\text{C}$  (blue triangles) at  $P_{\text{gas}} = 40$  bars, symbol size is indicative of particle size, and  
607 thresholds for deposit formation in terms of critical velocity. The powder impact conditions are intentionally  
608 outside of the calculated window of deposition used to print porous metallic deposits. (b) Normalized  
609 particle impact velocity ( $\eta$ ) as a function of particle diameter with the powder size distribution used in our  
610 experiments (45-105  $\mu\text{m}$ ) shaded in blue.  
611

612 **Figure 2:** Optical micrograph of cross sections of materials printed using (a) fast deposition, and (b) slow  
613 deposition (the red arrows on the left side of panel b show the interfaces between different passes). (c)  
614 Cross section optical micrograph of fast deposition at  $T=900\text{ }^{\circ}\text{C}$  showing similar structure to fast  
615 deposition at  $T=800\text{ }^{\circ}\text{C}$  but with less porosity (porosity  $27\pm 3$ ).

616 **Figure 3:** (a) Contact temperature as a function of particle impact velocity and diameter, where contact  
617 temperature increases with particle size (shaded area shows the range of velocities used experimentally to  
618 fabricate porous metal deposits). (b) Particle size distribution in 3D printed porous Ti-6Al-4V (fast  
619 deposition at  $800\text{ }^{\circ}\text{C}$ ).

620 **Figure 4:** Scanning electron micrographs of 3D printed Ti-6Al-4V parts. (a) Top view of a powder particle  
621 after impact. The arrows show lateral material flow at the periphery of the powder upon impact. (b) Cross  
622 section of powder after impact. (c) Magnified view of microstructure in undeformed region of powder  
623 depicted in (b). (d) Magnified view of refined microstructure at impact zone of powder depicted in (b).  
624 Frame pattern indicates the corresponding area in in the cross-section overview.  
625

626 **Figure 5:** Characterization of the 3D printed Ti-6Al-4V deposits in as-deposited condition and after heat  
627 treatment. (a) X-ray diffraction (XRD) pattern of as deposited and annealed samples. (b) Stress-strain  
628 behavior of as-deposited and annealed samples under compression loading.  
629

630 **Figure 6:** Post mortem fracture analysis of as deposited samples after compression loading showing  
631 fracture at interparticle boundaries on the (a) milli scale and (b) microscale.  
632

633 **Figure 7:** Relative compressive yield strength vs porosity of porous titanium structures fabricated by cold  
634 spray as well as SLM, EBM, DED and binderjet additive manufacturing technologies. Gibson-Ashby model  
635 is plotted. The data points with similar porosity to our samples are circled in the figure.  
636

637 **Figure 8:** Biocompatibility of murine preosteoblasts with Ti-6Al-4V metallic foam. (a-c) Representative  
638 LIVE (green, a)/DEAD (red, b) and Merged (c) confocal microscopy images of cells that grew within the  
639 first  $275\text{ }\mu\text{m}$  of a porous titanium substrate. Images are projection images of the average intensities from  
640 confocal microscopy image volumes of  $3.2\text{ mm} \times 3.2\text{ mm} \times 275\text{ }\mu\text{m}$ . (d) Rendering of a 3D image volume  
641 of preosteoblasts that grew  $275\text{ }\mu\text{m}$  into the Ti-6Al-4V porous deposit. (e) Murine preosteoblasts (live cells-  
642 green, cell nuclei-blue) growing around and between titanium powder. Ti-6Al-4V particles are the spherical  
643 black voids within the image. (f) SEM images of cells on surfaces of 3D printed Ti-6Al-4V powders. (g)  
644 Magnified view of cells on 3D printed porous titanium.

645 **Table captions:**

646 Table VI: Constant values for calculating contact temperature at impact zone according to Equation 1.  
647

648 Table VII: Ti-6Al-4V properties for finite element simulation [35].  
649

650 Table VIII: Experimental conditions used for cold spray deposition of titanium powders. Process gas  
651 pressure (40 bar), process gas (nitrogen) and number of passes (5) were kept constant, while temperature  
652 and scan velocity were varied. Porosity from image analysis and Archimedes' principal are reported in the  
653 last two columns, respectively.

654 Table IX: Comparison of compressive yield strengths of Ti and Ti-6Al-4V porous structures

655 Table X: Surface roughness parameters of bulk titanium substrates and 3D printed Ti-6Al-4V deposits. \*  
656 Parameters are according to ISO 4278 geometrical product specification. Sa : Arithmetic average, Sq :  
657 Root mean square, Sv : Maximum valley depth, Sp : Maximum peak height