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# **Continuum damage mechanics in SPH based on particle interaction area.**

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# Overview

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- Introduction
  - Smoothed Particle Hydrodynamics (SPH)
  - Continuum damage mechanics
- Forming a new free surface within SPH
- Particle interaction area concept
- Implementation and test of interaction area concept
  - Plate impact and damage model used
  - 1D and 3D plate impact models
- Summary

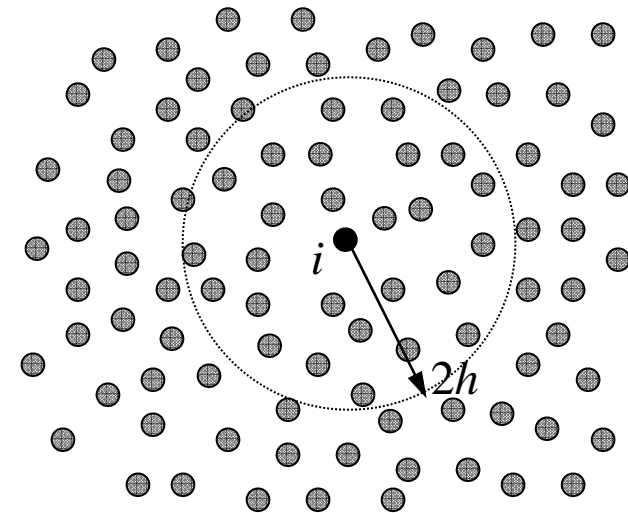
# Smoothed Particle Hydrodynamics (SPH)

- SPH is a numerical technique for the approximate integration of the governing equations of continuum mechanics.
- It is a meshless Lagrangian method (the points move with the material) that uses pseudo-particle interpolation to compute smooth field variables.
- If a function  $f(x)$  is known at  $N$  discrete points (known as particles), it can be approximated by the summation:

$$\langle f(x) \rangle \approx \sum_{j=1}^N \frac{m_j}{\rho_j} f(x_j) W(x - x_j, h)$$

- The kernel function  $W$  has compact support and so the value of the function at a point depends only on the particles within the support domain of the point.
- The gradient of the function can be approximated as:

$$\langle \nabla f(x) \rangle \approx \sum_{j=1}^N \frac{m_j}{\rho_j} f(x_j) \nabla W(x - x_j, h)$$



# Smoothed Particle Hydrodynamics (SPH)

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- The governing equations of continuum mechanics can be written in SPH form as:

$$\left\langle \frac{d\rho_i}{dt} \right\rangle = \rho_i \sum_j \frac{m_j}{\rho_j} [v_i - v_j] \nabla_i W_{ij} \quad \text{Conservation of mass}$$

$$\left\langle \frac{dv_i}{dt} \right\rangle = \sum_j m_j \left[ \frac{\sigma_i}{\rho_i^2} + \frac{\sigma_j}{\rho_j^2} \right] \nabla_i W_{ij} \quad \text{Conservation of momentum}$$

$$\left\langle \frac{dE_i}{dt} \right\rangle = -\frac{\sigma_i}{\rho_i^2} \sum_j m_j [v_i - v_j] \nabla_i W_{ij} \quad \text{Conservation of energy}$$

- where the summation is over all neighbour particles and  $m_j$  is the mass of particle  $j$ .

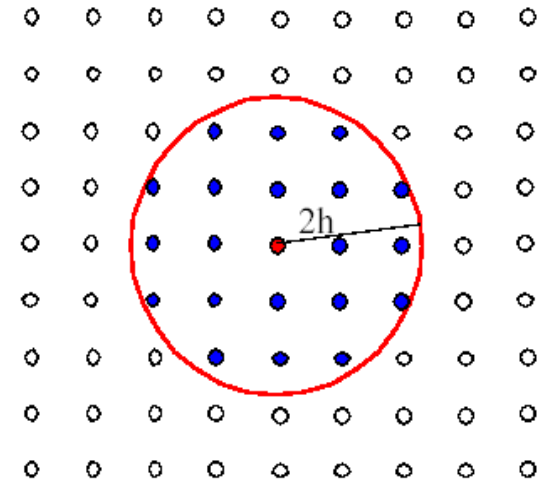
# Smoothed Particle Hydrodynamics (SPH)

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- In this work we use the Total Lagrangian<sup>1</sup> form of SPH.
  - The conservation equations are written and solved in the material coordinate system,  $X$ , instead of the spatial coordinate system,  $x$ .
  - The relationship between the two coordinate systems is given by the deformation gradient tensor  $\mathbf{F}$ .
  - The conservation of momentum equation is therefore written

$$\left\langle \frac{dv_i}{dt} \right\rangle = \sum_j m_j \left[ \frac{\mathbf{N}_i}{\rho_i^2} + \frac{\mathbf{N}_j}{\rho_j^2} \right] \nabla_i W(X_i - X_j, h_0)$$

- Where  $\mathbf{N} = (\mathbf{J}\mathbf{F}^{-1}\boldsymbol{\sigma})$  is the nominal stress and  $J = \det \mathbf{F}$



<sup>1</sup>R Vignjevic, JR Reveles, JC Campbell, 2006. SPH in a total Lagrangian formalism. *CMES*, 14(3), 181-198.

# Continuum Damage Mechanics

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- Continuum damage mechanics (CDM) is an approach for modelling the effect of material damage within the framework of continuum mechanics.
- Underlying concept:
  - mechanical damage in solid materials is due to the creation and growth of micro-cracks or micro-voids.
  - the characteristic length of the cracks is too small to individually represent
  - their influence is homogenised, so the effect of damage is averaged over a volume and represented by a continuous variable related to the density of the defects.
- Considering a 1D problem where a volume element of material is loaded by force  $F$ . A scalar damage variable,  $D$ , represents the reduction in the cross-section area,  $S$ .

$$D = \frac{S - \tilde{S}}{S}$$

- An effective Cauchy stress,  $\tilde{\sigma}$ , can then be defined as the stress acting on the effective surface area.

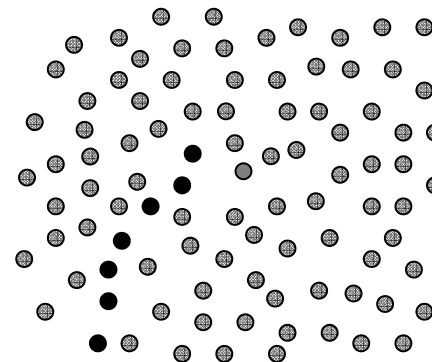
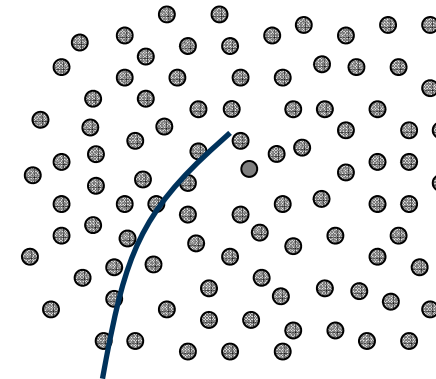
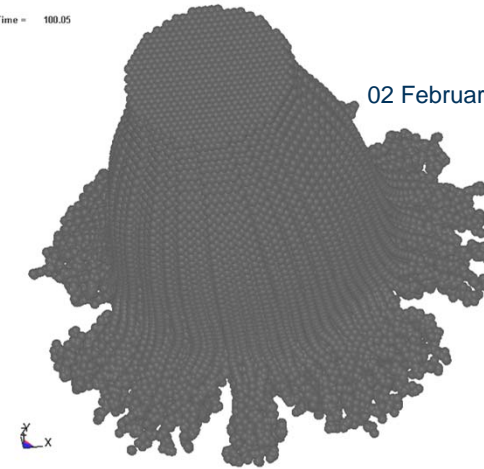
$$\tilde{\sigma} = \frac{\sigma}{(1 - D)}$$

# Forming a new free surface

- When the damage variable reaches a critical value, it is assumed that the cracks and voids coalesce to form a new free surface.
- Several approaches are available to describe and treat a new free surface within the original domain.
  - Treat new free surface as geometrical object.
    - Describe geometry of free surface using level set (or similar) modify method to treat resulting discontinuity.
  - Represent free surface as combination of local failures
    - Set failed particle stress to zero

Time = 100.05

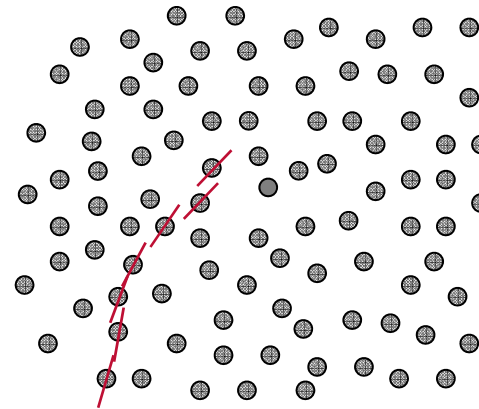
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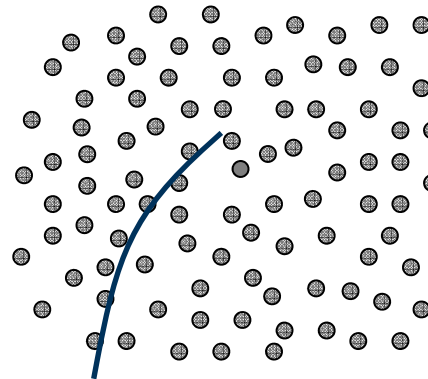
# Forming a new free surface

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- Represent free surface as combination of local failures
  - Cracked particle approach<sup>1</sup> where failed particle is split in two.



- Modify particle-particle interaction
  - basis of work presented here



<sup>1</sup>T Rabczuk and T Belytschko. 2004. Cracking particles: A simplified meshfree method for arbitrary evolving cracks. *IJNME*,



# Particle interaction area

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- The concept of area vectors within the SPH method was outlined by Swegle<sup>1</sup> for the purpose of discussing the tensile instability inherent in any basic SPH description.
- Swegle noted that the fundamental definition of the stress tensor shows that a force exerted on a surface due to stress is given by:

$$\mathbf{F} = \boldsymbol{\sigma} \cdot \mathbf{A}$$

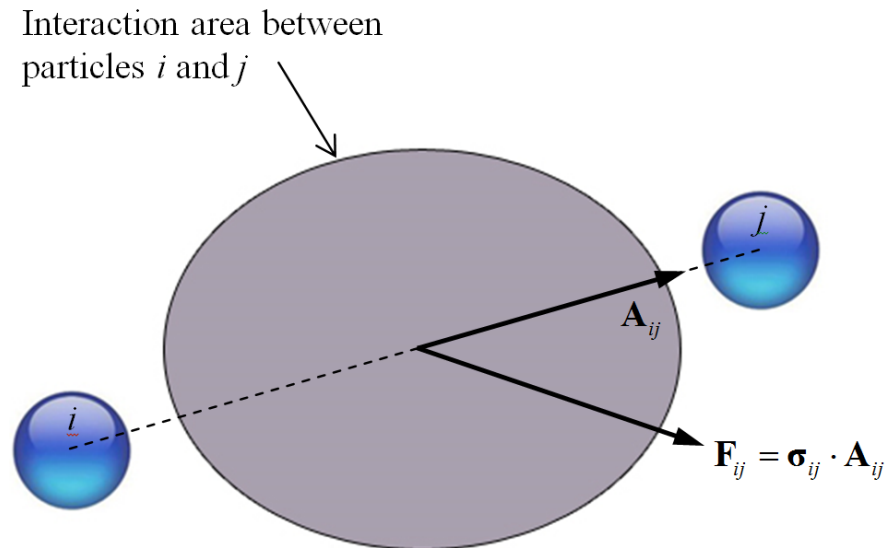
- The conservation of momentum equation can be rewritten as

$$F_i = m_i a_i = - \sum_j m_i m_j \left[ \frac{\boldsymbol{\sigma}_i}{\rho_i^2} + \frac{\boldsymbol{\sigma}_j}{\rho_j^2} \right] \nabla_i W_{ij}$$

- Rearranging allows the definition of an interaction area.

$$F_i = - \sum_j \left[ (\boldsymbol{\sigma}_i) \frac{\rho_j}{\rho_i} + (\boldsymbol{\sigma}_j) \frac{\rho_i}{\rho_j} \right] A_{ij}$$

$$A_{ij} = V_i V_j \nabla_i W_{ij}$$



<sup>1</sup>J W Swegle. Conservation of momentum and tensile instability in particle methods. USA: Sandia National Laboratories, 2000. SAND2000-1223

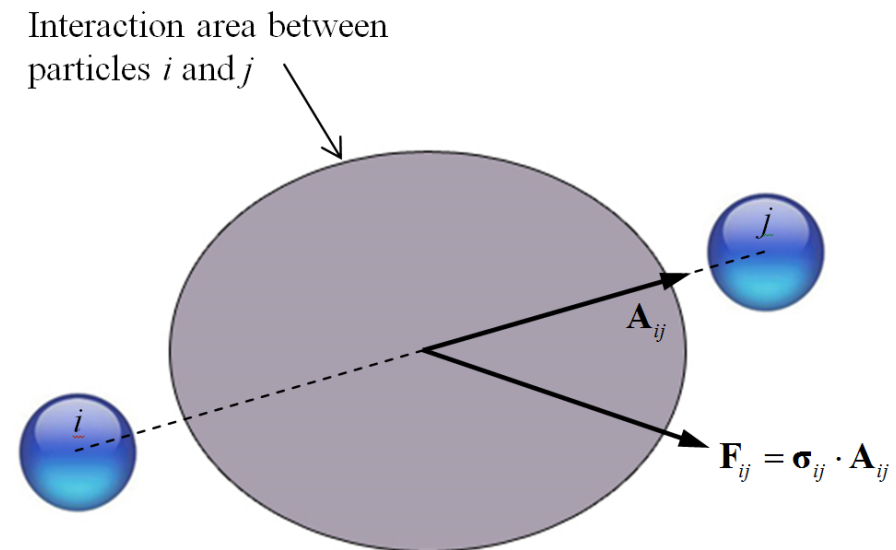
# Particle interaction area

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- Apply damage to this interaction area,

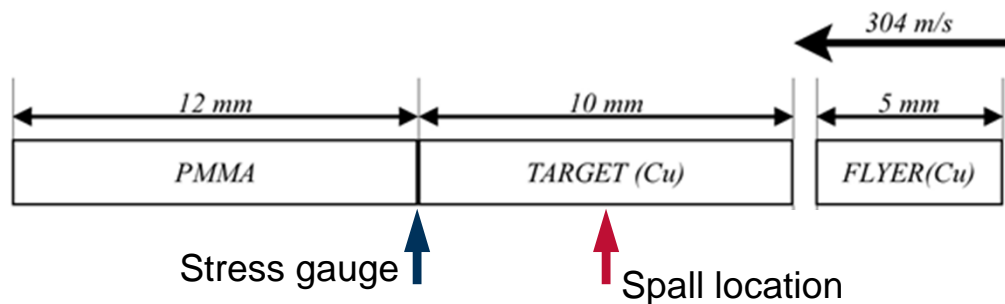
$$F_i = -\sum_j \left[ (\boldsymbol{\sigma}_i) \frac{\rho_j}{\rho_i} + (\boldsymbol{\sigma}_j) \frac{\rho_i}{\rho_j} \right] A_{ij} (1 - D_{ij})$$

- when damage reaches its critical value the interaction area is assumed to be zero
- Consistent with CDM, so can use damage laws derived for CDM

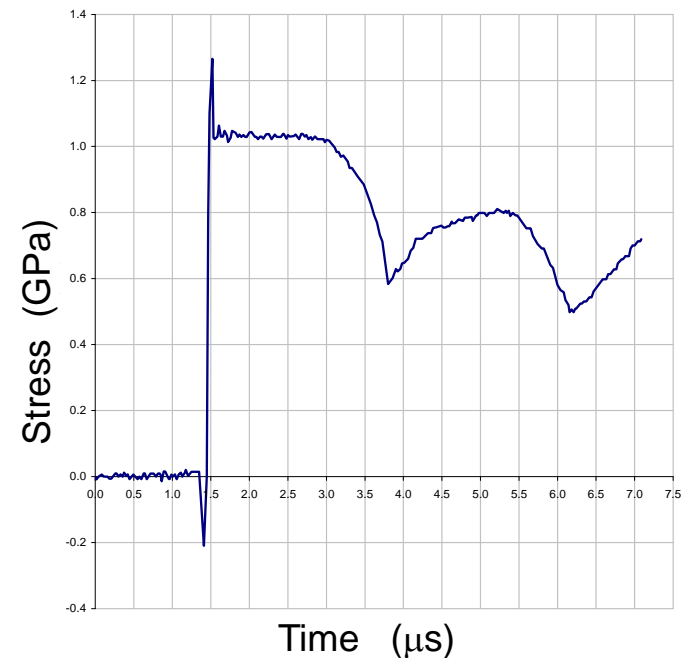
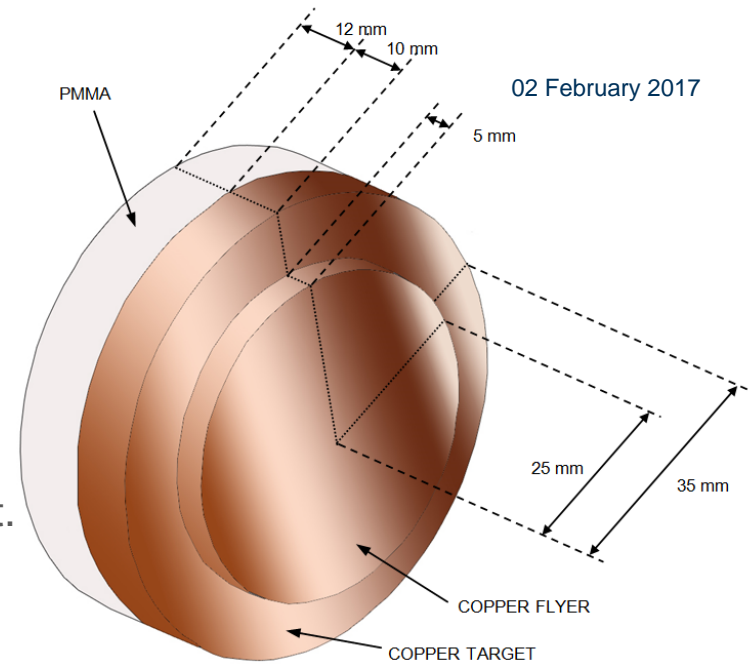


# Test problem

- To investigate the behaviour of the interaction area concept we have used 1D, 2D and 3D models of a flyer plate experiment.
- 304 m/s impact of a copper flyer on a copper target.
- Stress gauge mounted in PMMA at interface with copper target.
- Spall plane formed at centre of target plate, pullback signal visible is stress trace.



- Axis of flyer and plate is under 1D strain for duration of initial impact and formation of spall plane



# Cochran-Banner spall model

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- The Cochran-Banner<sup>1</sup> spall model was used as the damage model for this investigation.
- The model assumes all changes in volume past the material spall strength is due to micro-crack and void growth:

$$D(x,t) = \int_0^t dV/A \quad dV > 0$$

- For a bond the volume change is assumed to be the average of the two particles

$$\Delta V_{ij} = \frac{dt}{2} (V_i \text{tr } \dot{\boldsymbol{\epsilon}}_i + V_j \text{tr } \dot{\boldsymbol{\epsilon}}_j)$$

- The increment in damage is then

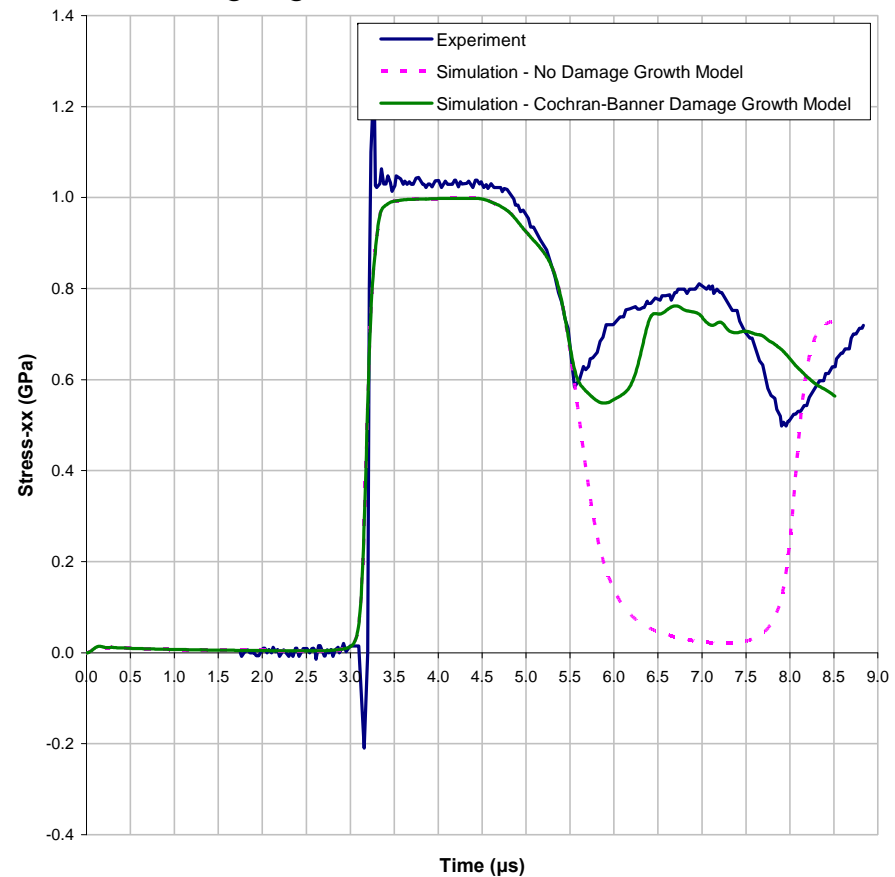
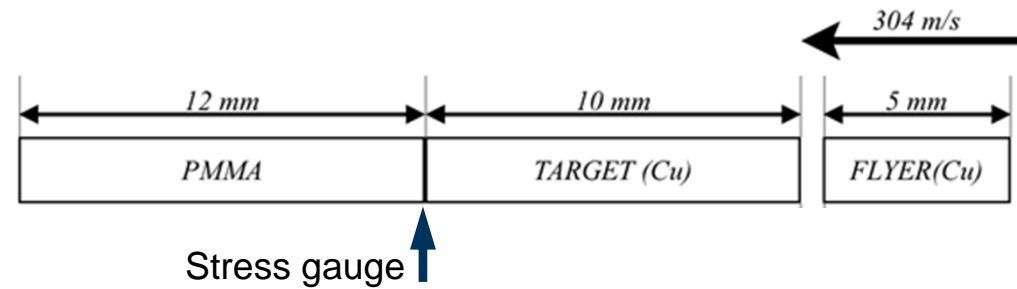
$$\Delta D_{CB} = \frac{\Delta V_{ij}}{|A_{ij}|}$$

<sup>1</sup>S Cochran, D Banner. Spall Studies in Uranium. *J Appl Phys* 1977;48(7):2729-2737

# Plate impact model – 1D solver

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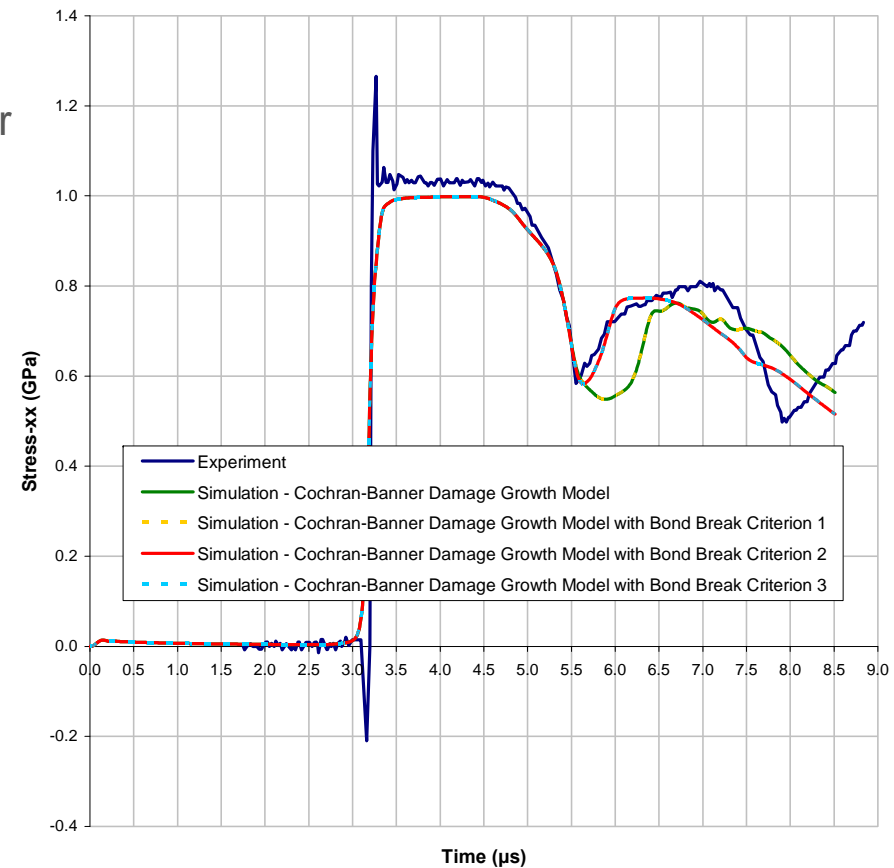
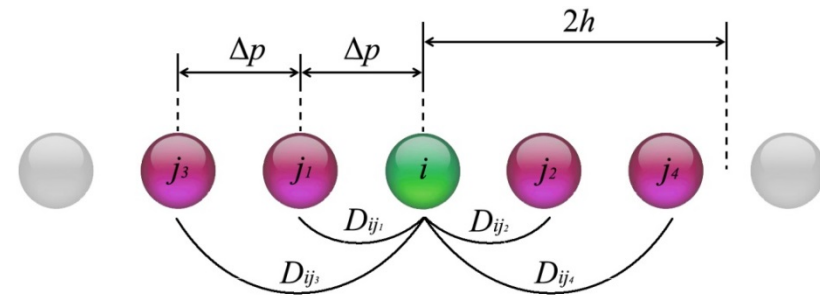
- Without damage model no spall occurs
- With damage model spall occurs at correct location within target
- Shape of pullback signal is not correct



# Plate impact model – 1D solver

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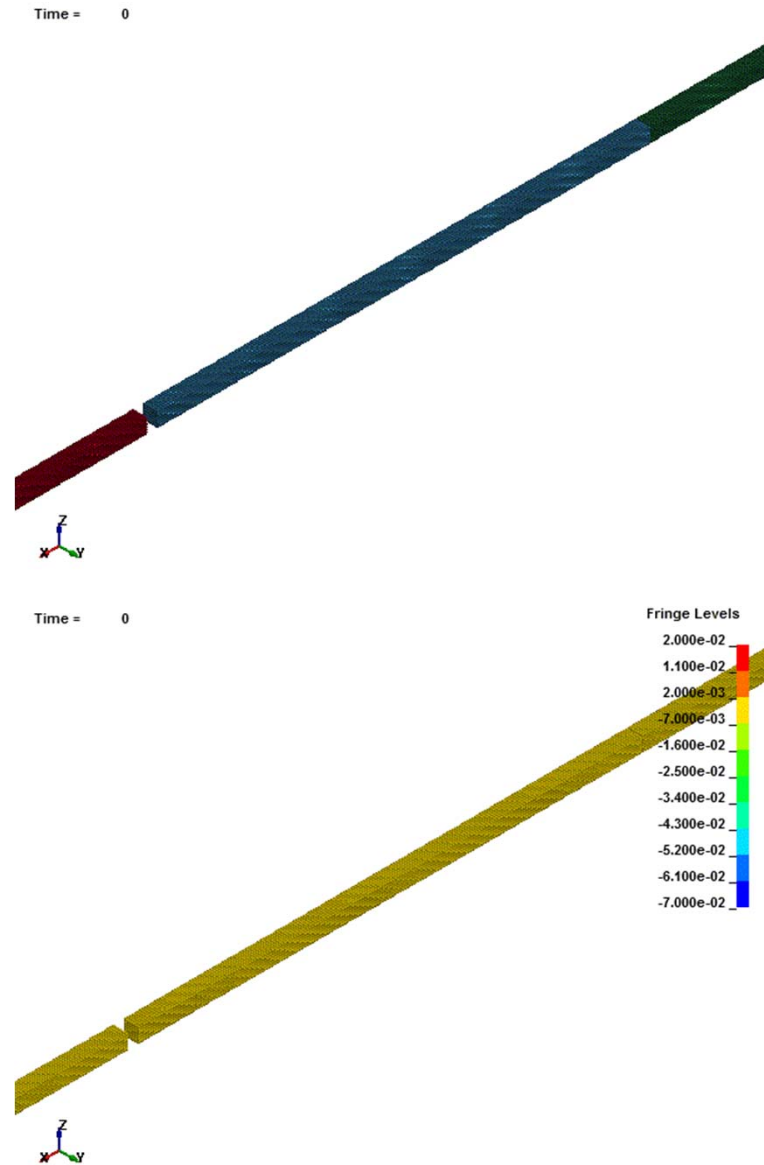
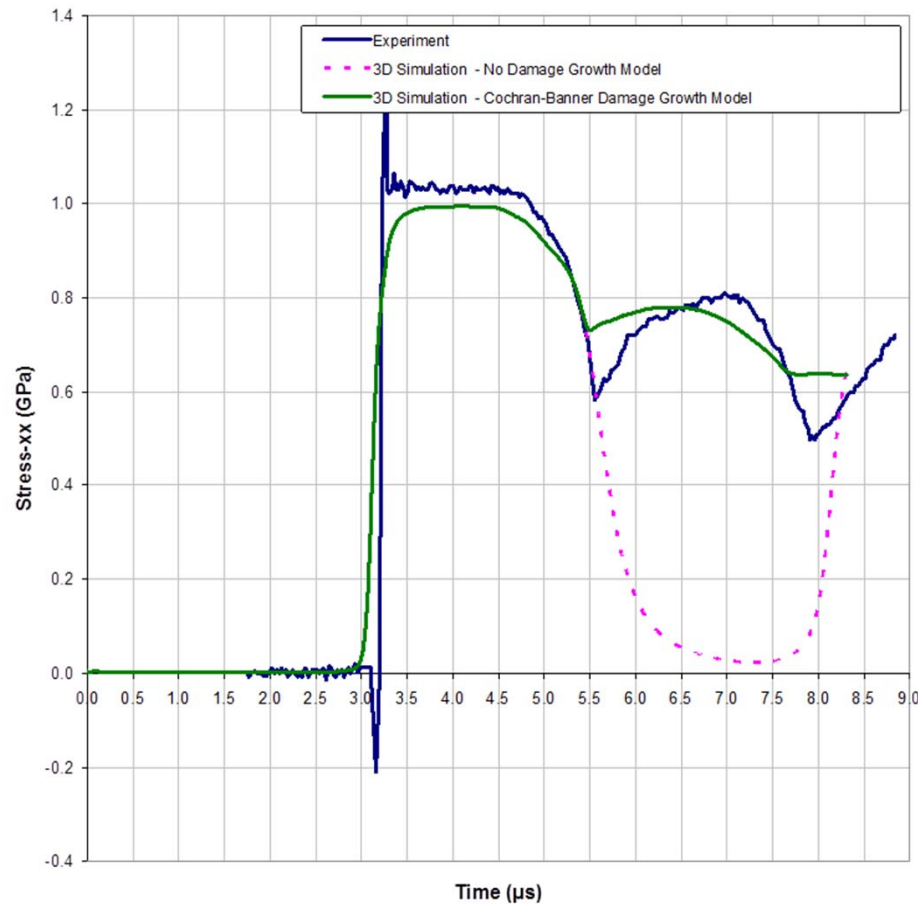
- A given  $i$  particle interacts with multiple neighbours in a given direction
- Investigated three criteria for influence of multiple neighbours:
  1. if 1<sup>st</sup> neighbour failed then 2<sup>nd</sup> neighbour is also failed
  2. if 2<sup>nd</sup> neighbour failed then 1<sup>st</sup> neighbour is also failed
  3. If either fails then other bond is also failed



# Plate impact model – 3D solver

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- 3D solver, symmetry boundary conditions to enforce 1D strain state



# Summary

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- Meshless methods offer several approaches to treatment of material damage and failure within the numerical model
- We are investigating the concept of treating damage at the particle-particle interaction level
- Concept of interaction area offers natural approach to treatment of damage based on continuum damage mechanics framework
- Initial tests in 1D and 3D demonstrate feasibility of approach.
- Further work is required to understand influence of damage in neighbour particle-particle bonds in 2D and 3D and investigate ability to represent more geometrically complex failure .